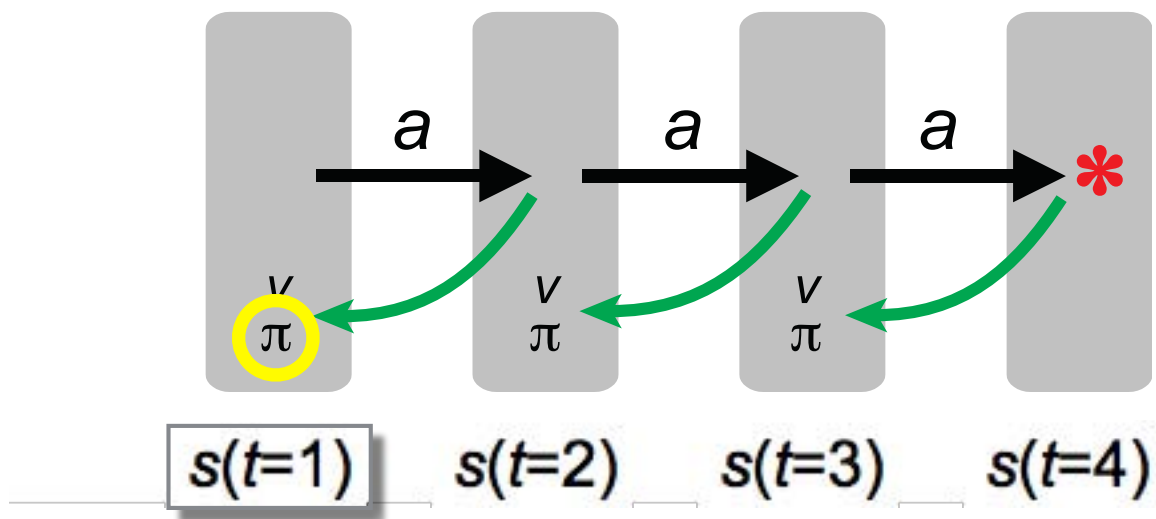
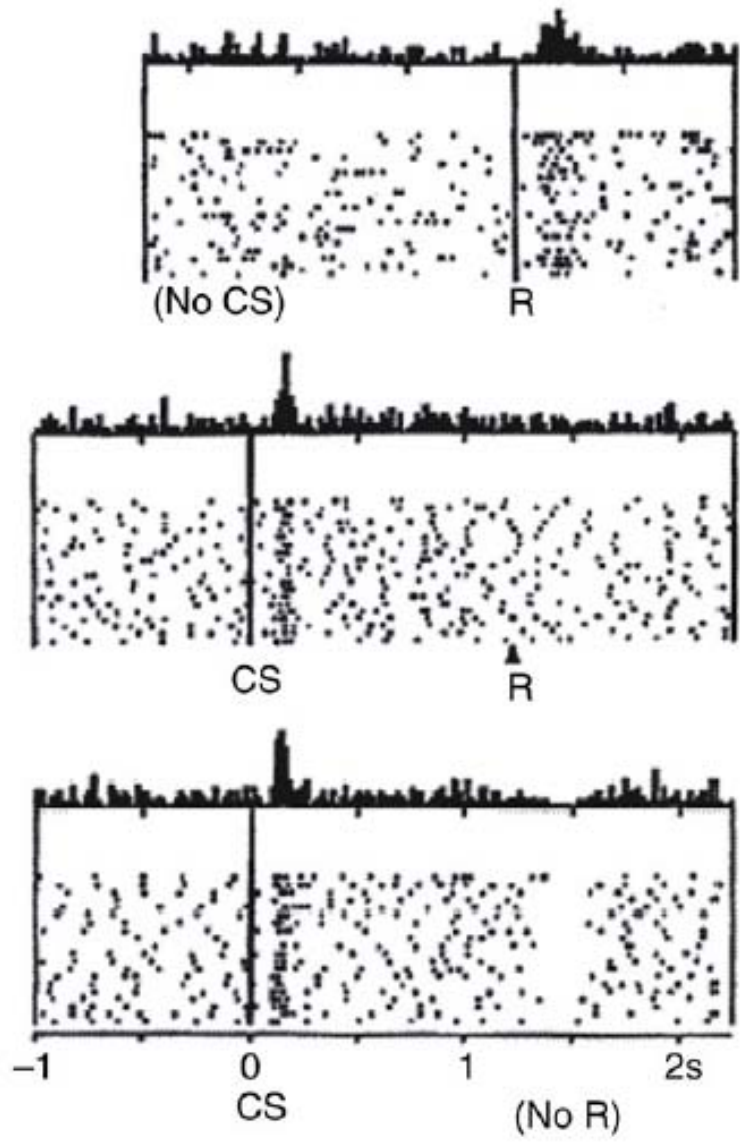


Hierarchical Reinforcement Learning and Human Behavior

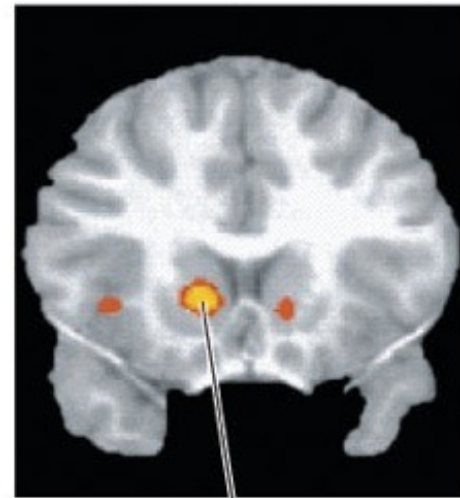
Matthew Botvinick
Princeton Neuroscience Institute
and Department of Psychology
Princeton University



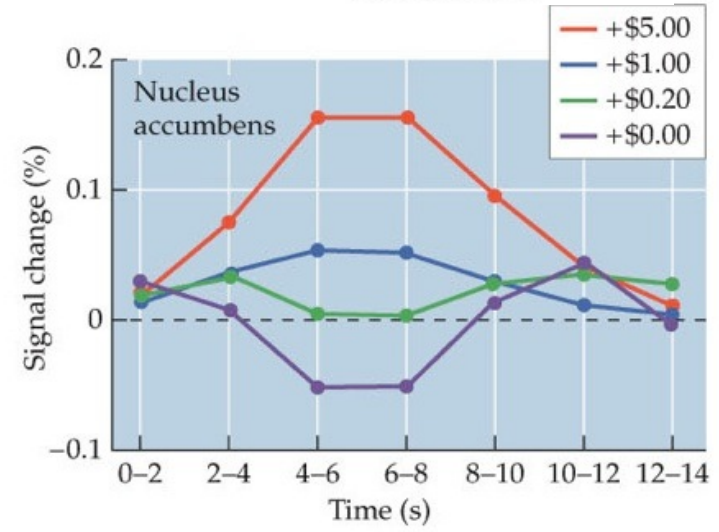




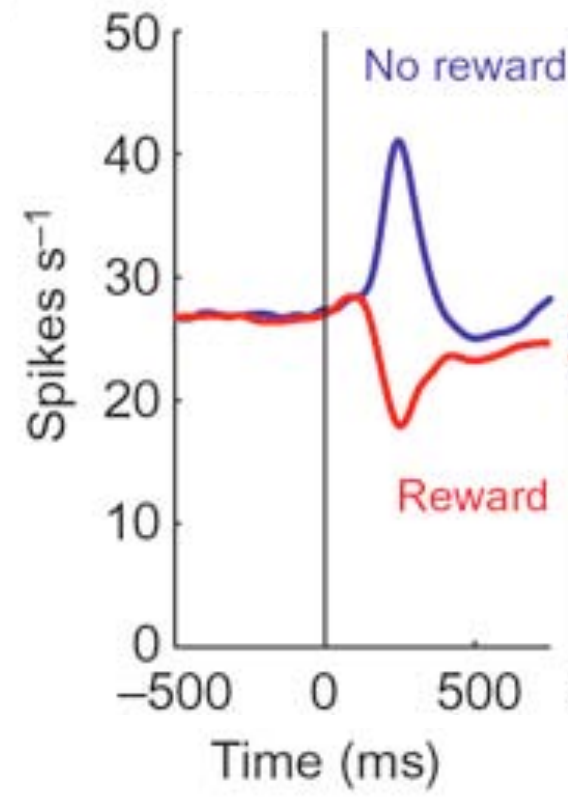
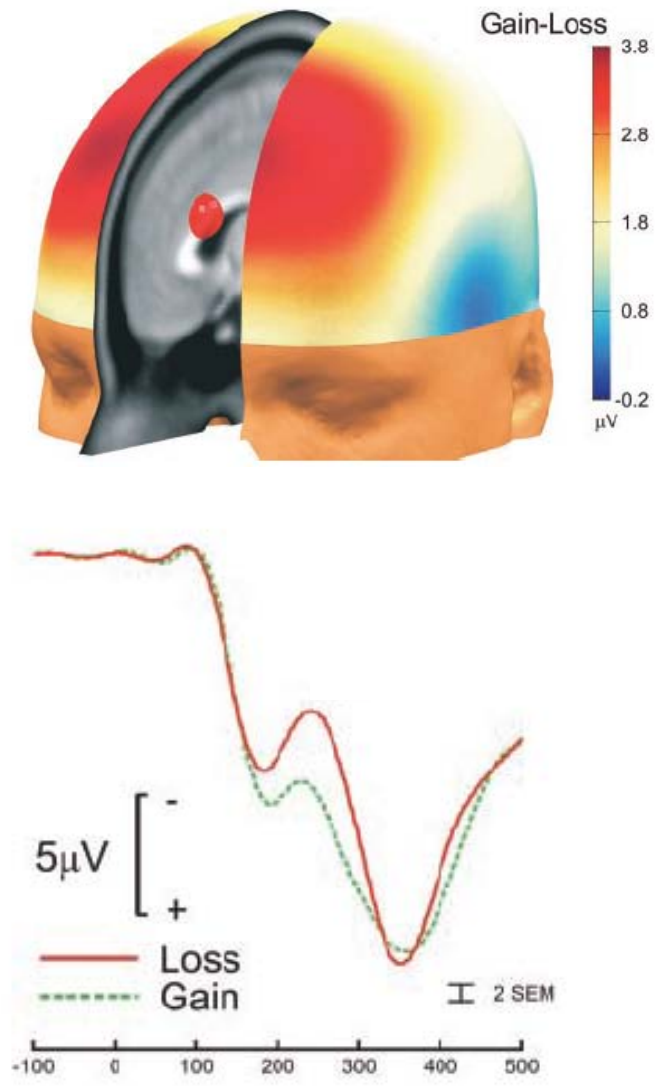
Schultz et al., *Science*, 1997



Nucleus accumbens



Knutson et al., *NeuroReport*, 2001



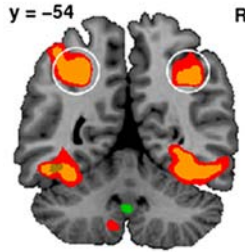
Matsumoto & Hikosaka, *Nature*, 2007

Gehring & Willoughby, *Science*, 2002

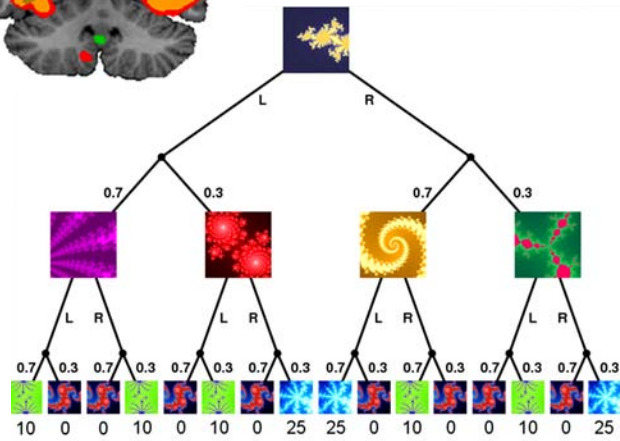
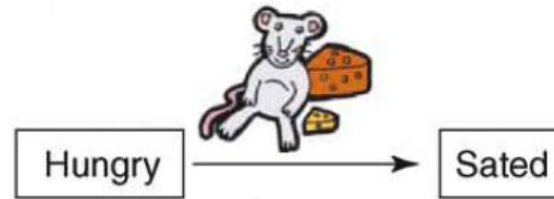
Phase 1 - Training:



State Prediction Error

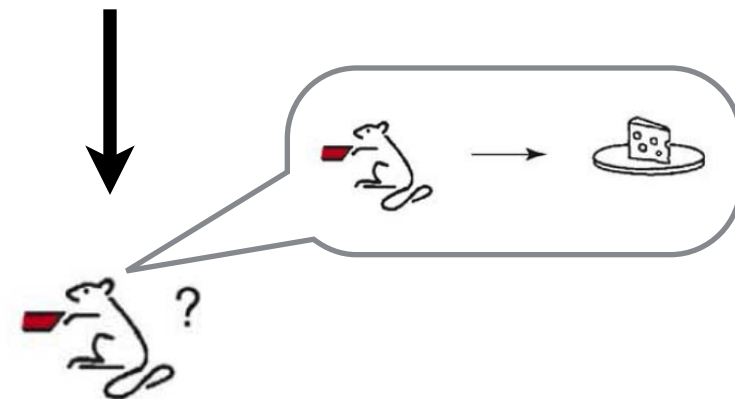


Phase 2 - Motivational shift:

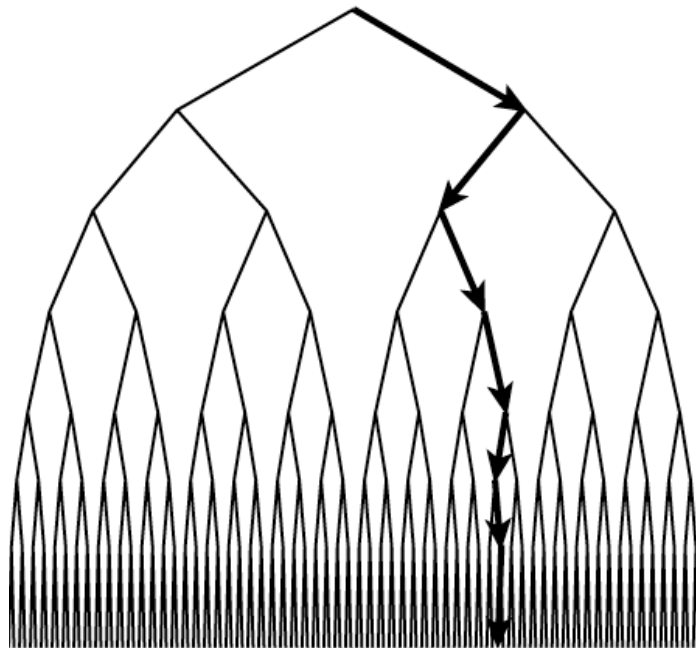


From Glaser, Daw, Dayan & O'Doherty, 2010

Phase 3 - Test:
(extinction)



From Niv, Joel & Dayan, *TICS*, 2006 (artwork by B. Balleine)



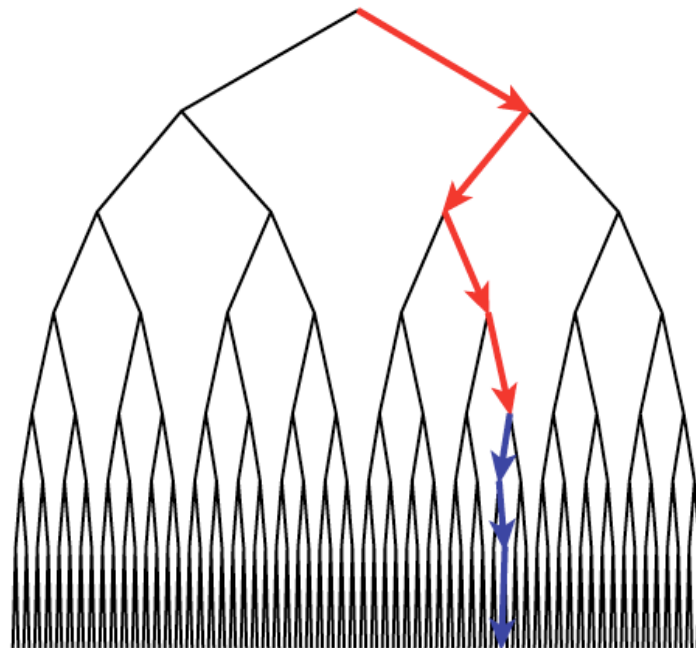
0.8%





The Curse of Dimensionality

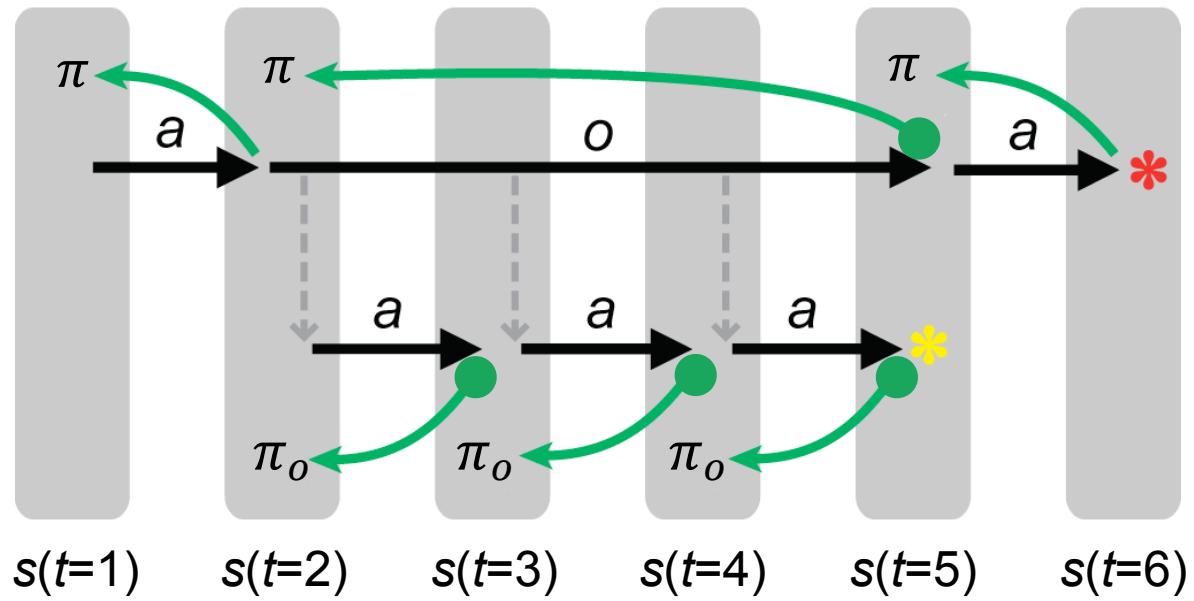


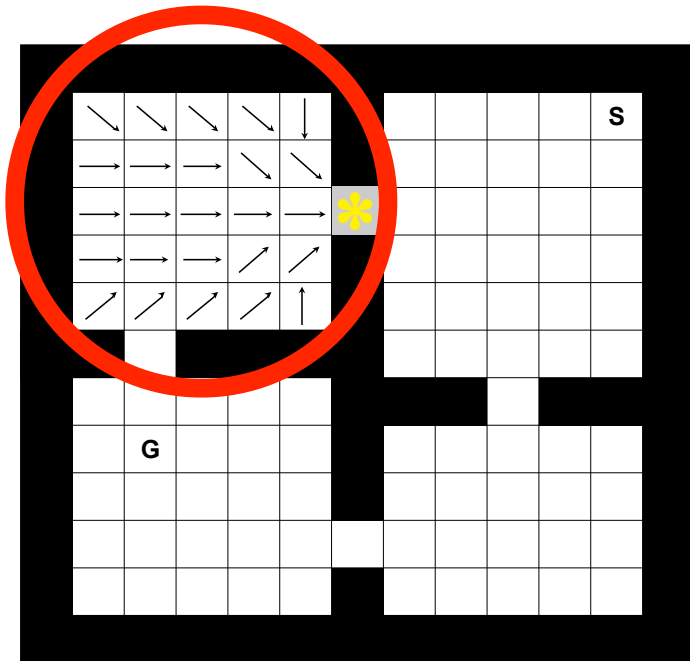


15.6%

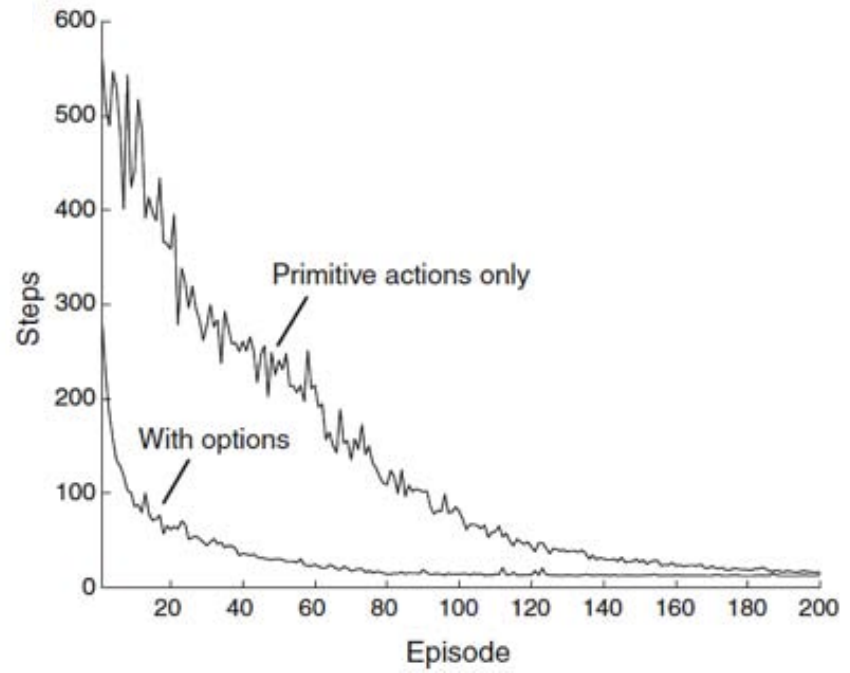


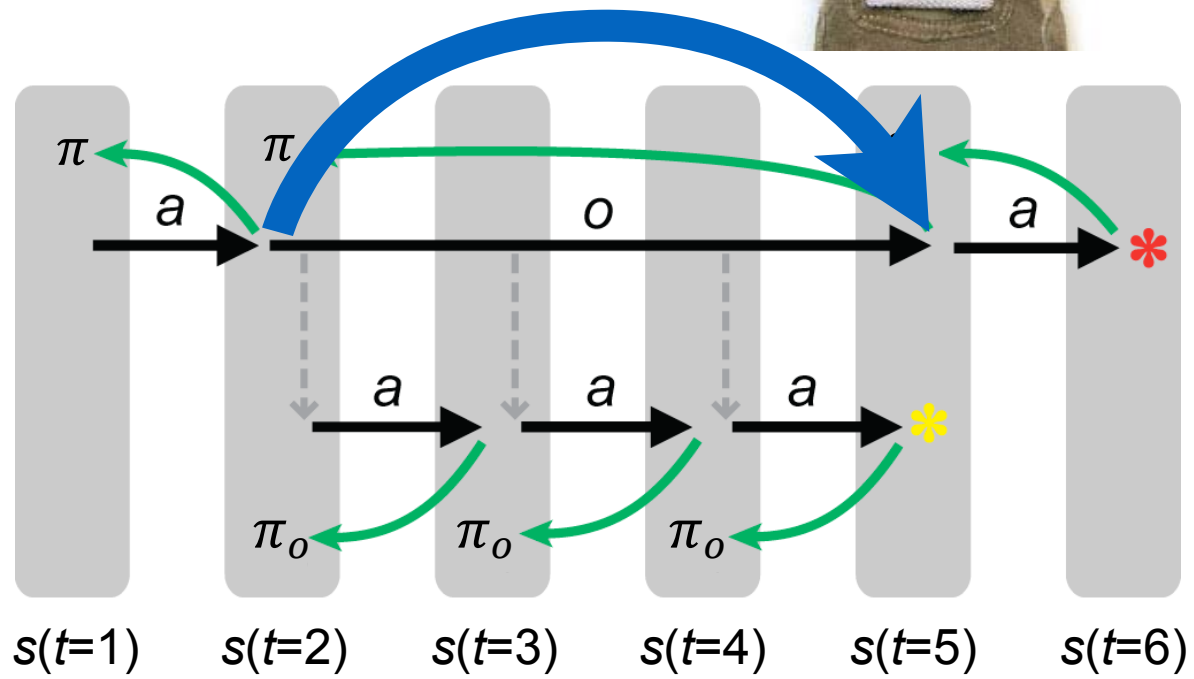
The Blessing of Abstraction

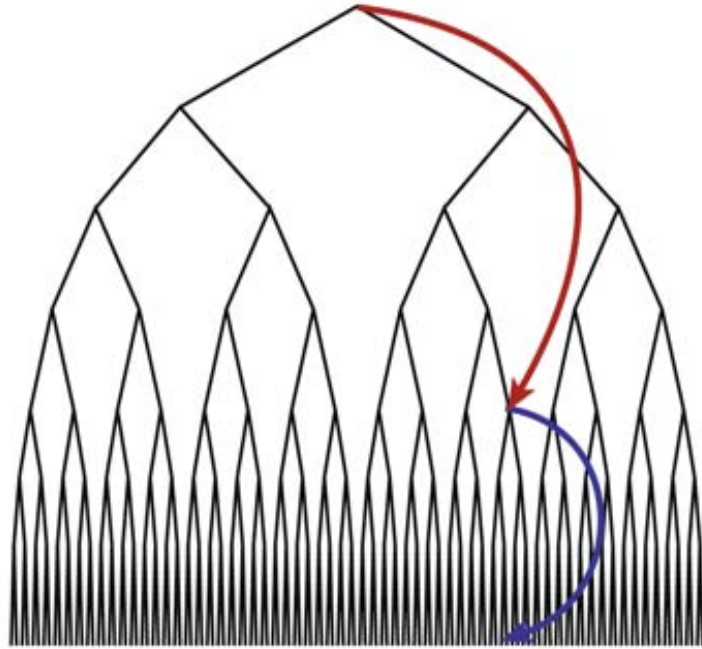


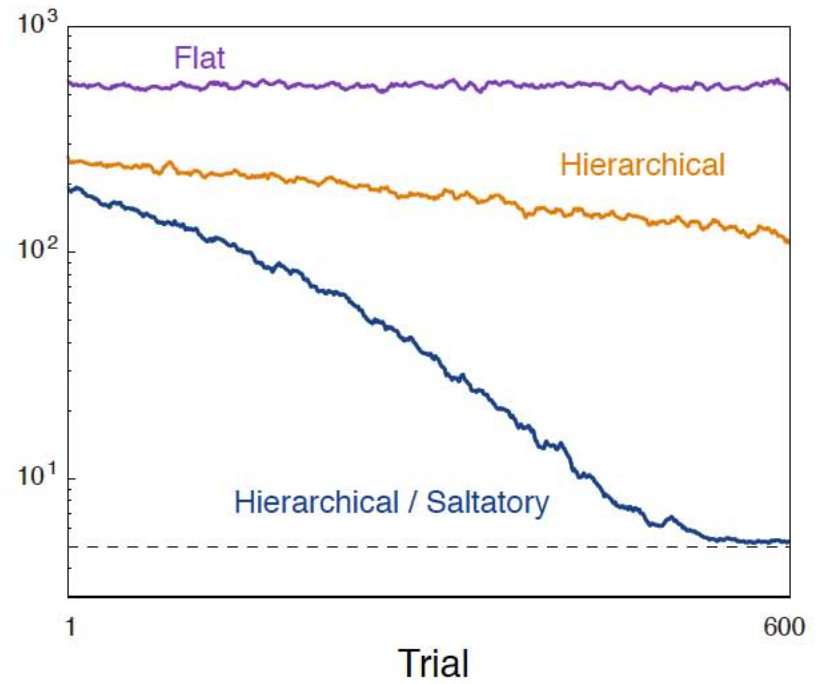
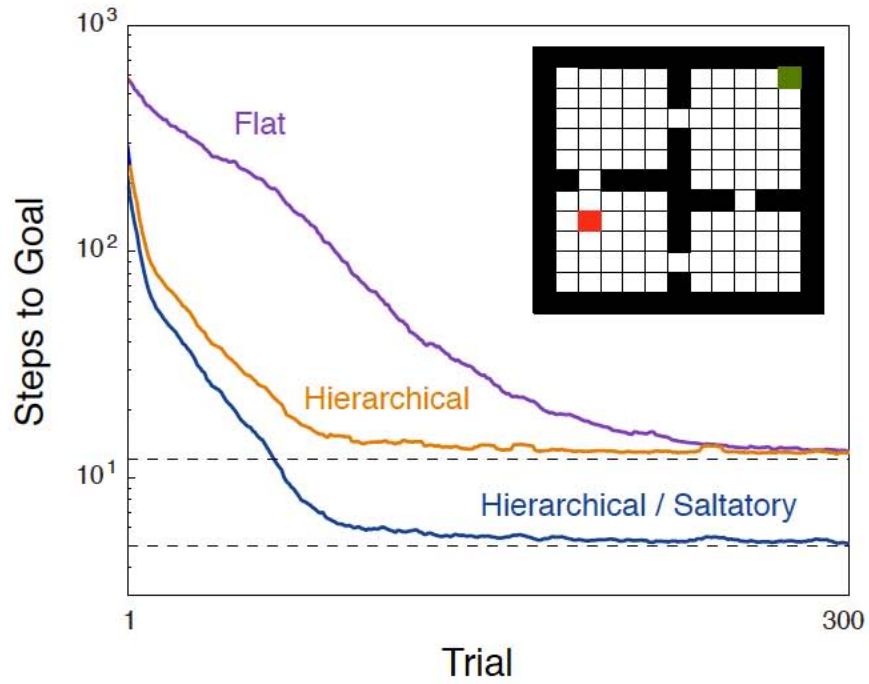


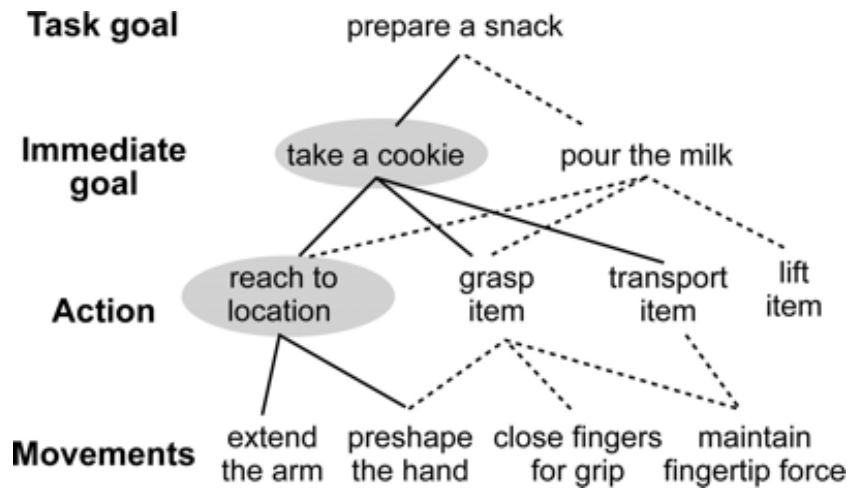
After Sutton, Precup & Singh, 1999





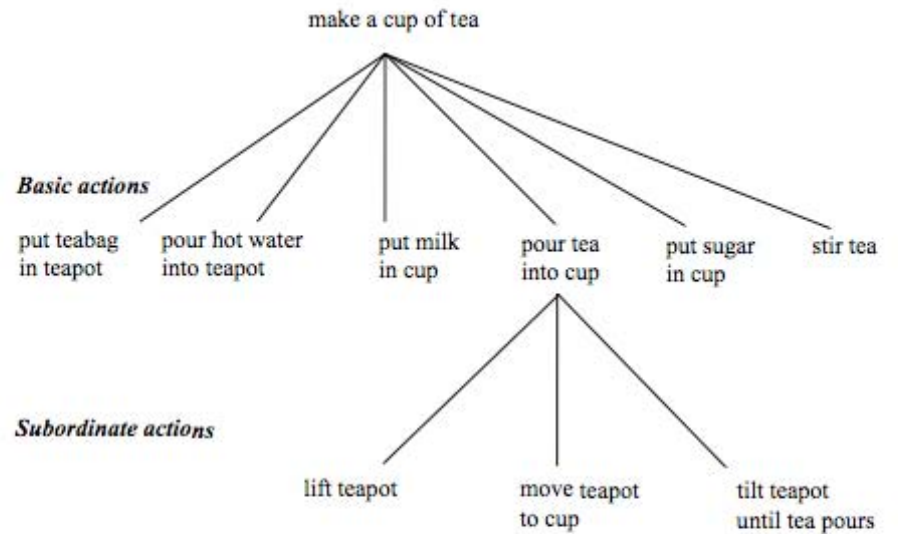




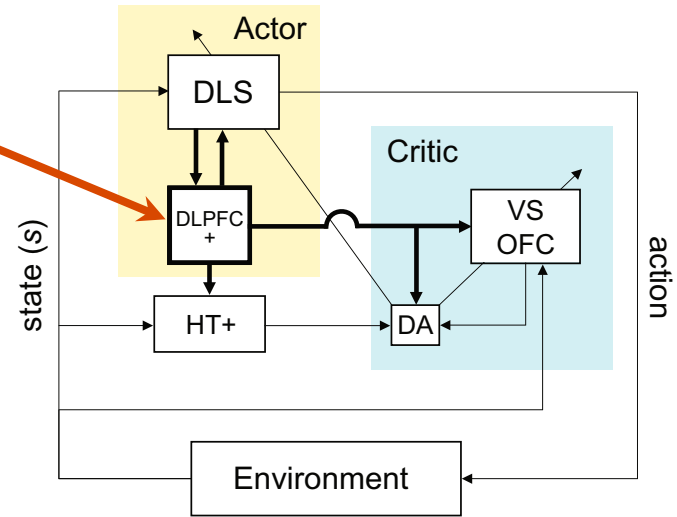
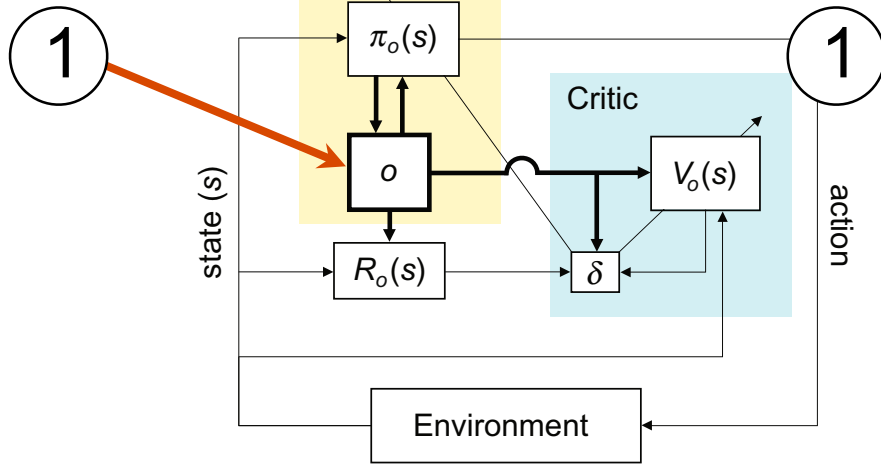
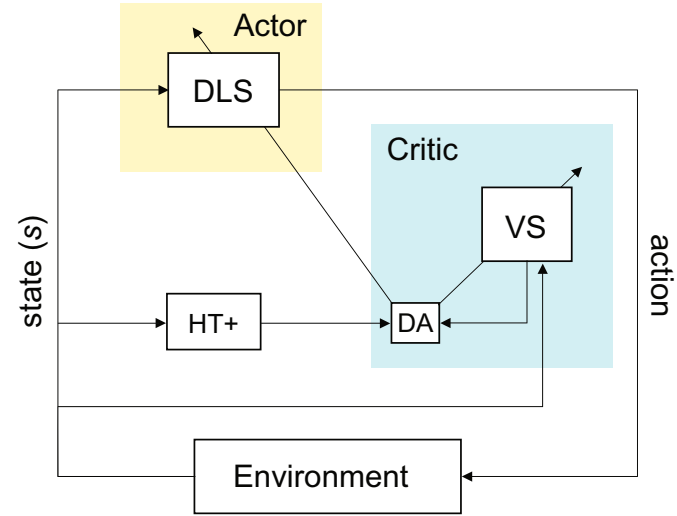
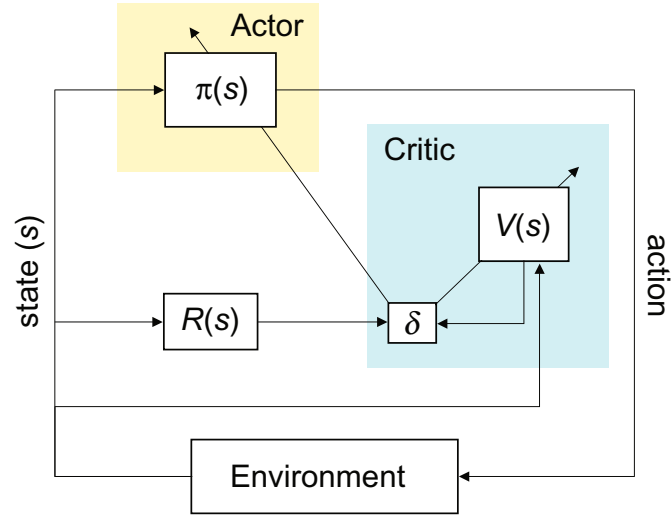


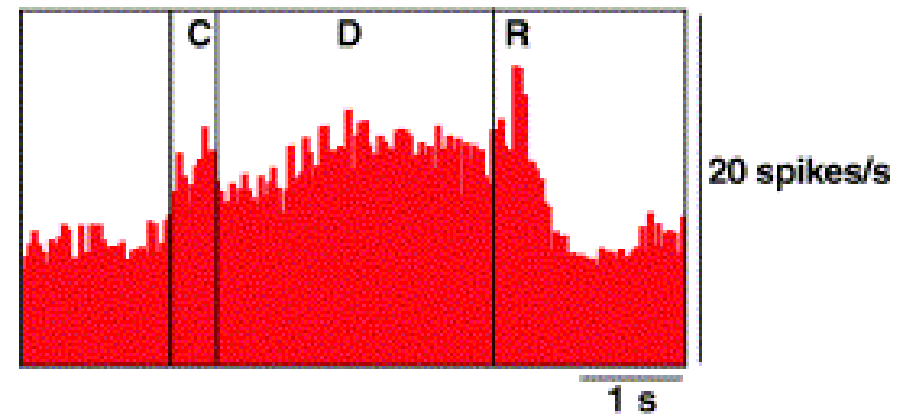
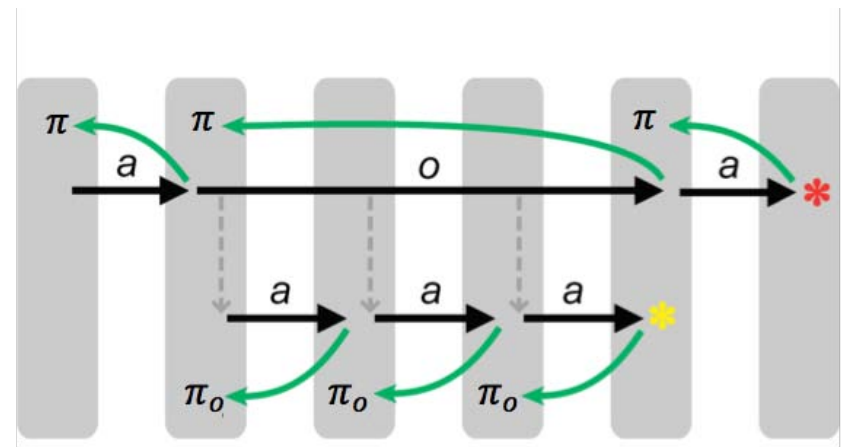
Hamilton & Grafton, *J Neurosci*, 2006

Superordinate actions

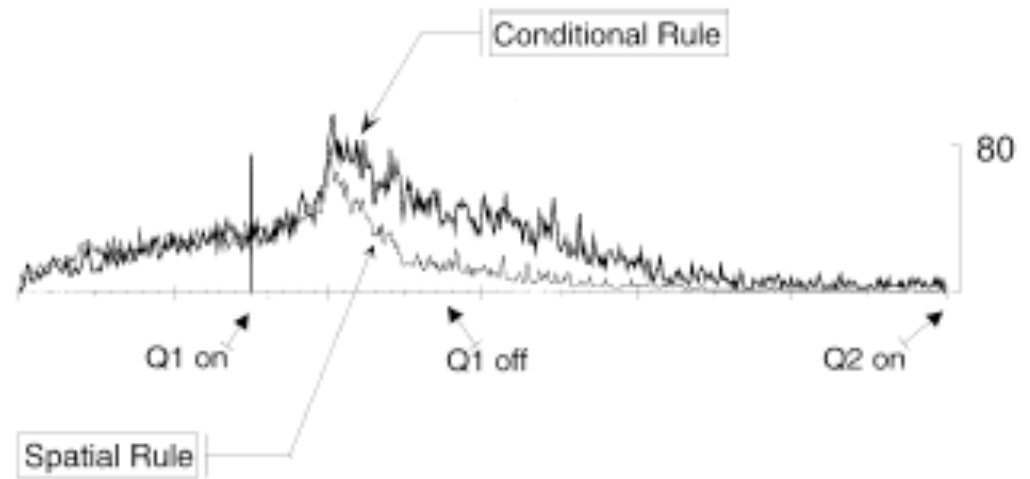
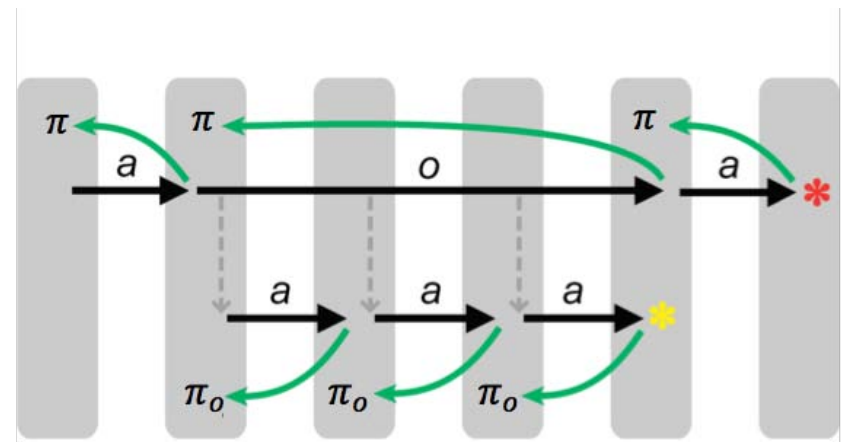


Humphreys & Forde, *Cog. Neuropsych.*, 2001

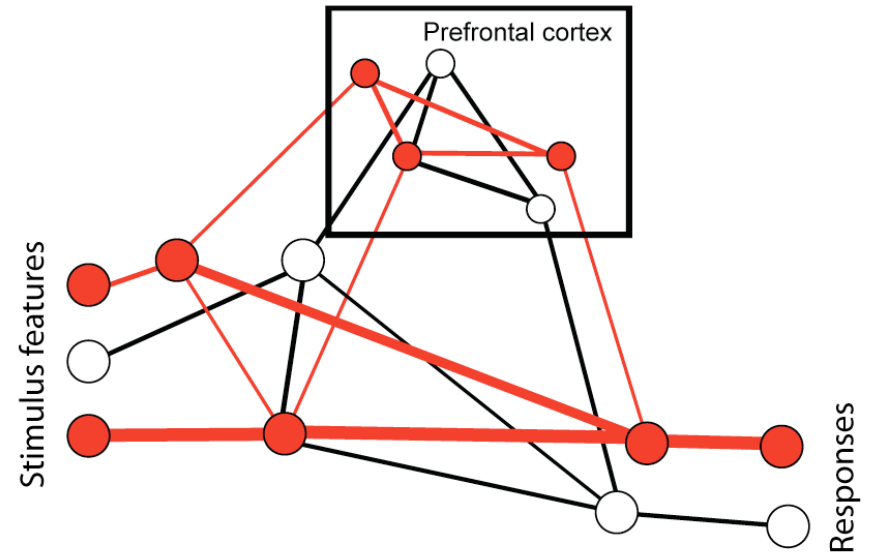
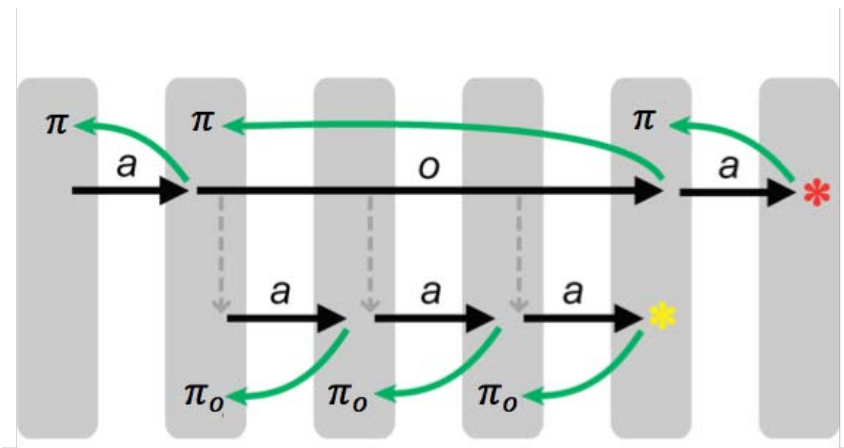




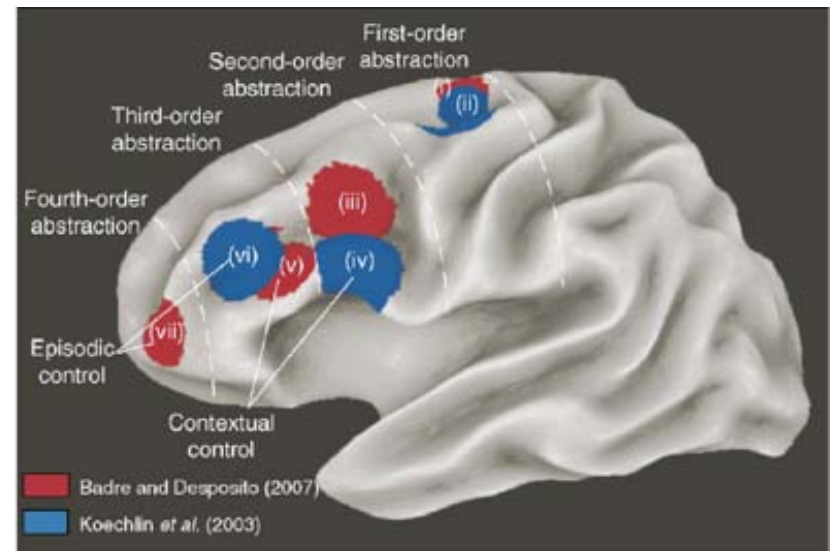
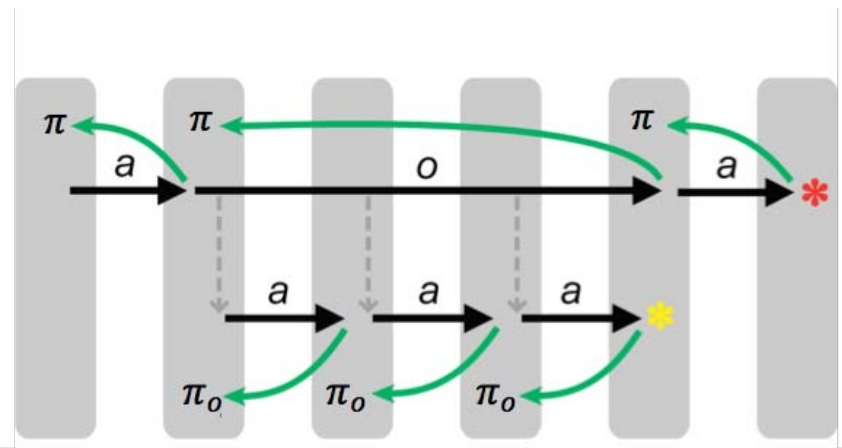
From Curtis & D'Esposito, *TICS*, 2003



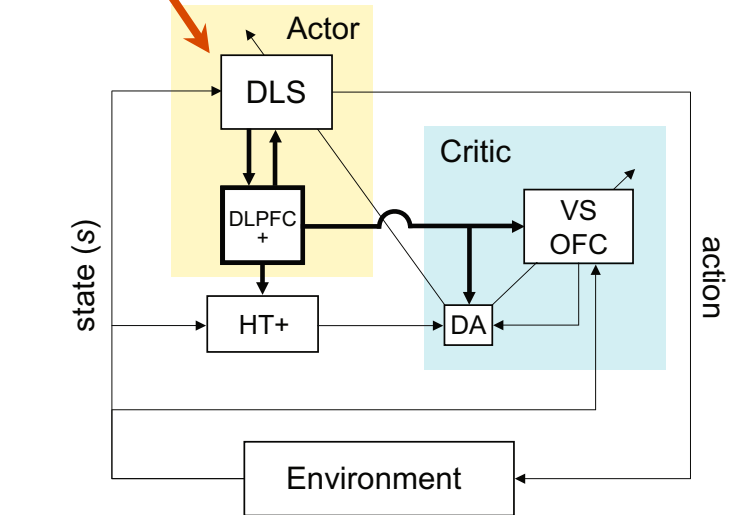
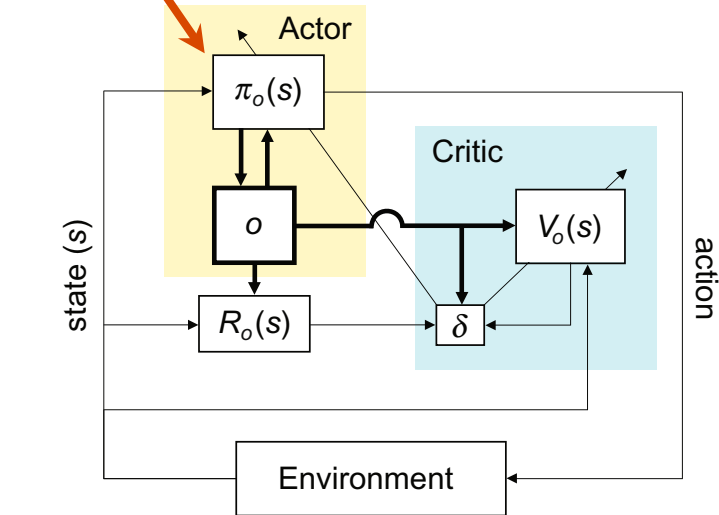
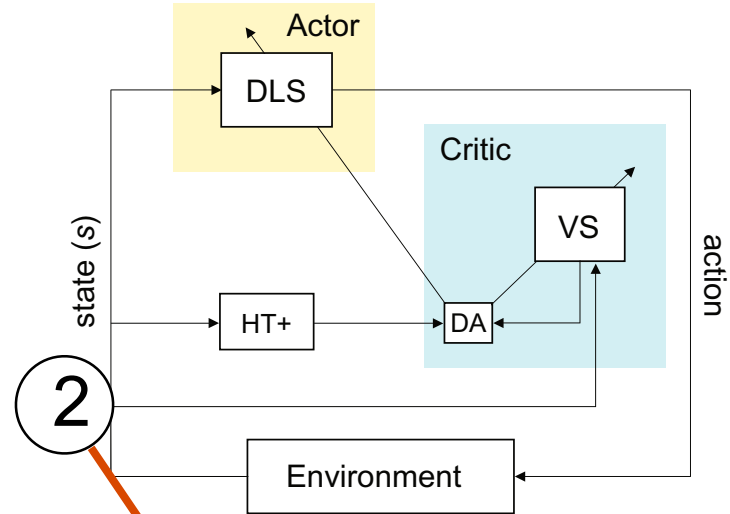
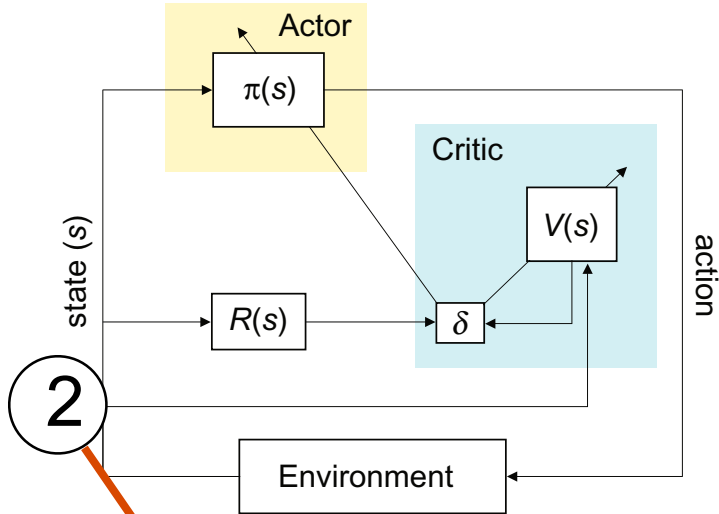
White & Wise, *Exp Br Res*, 1999

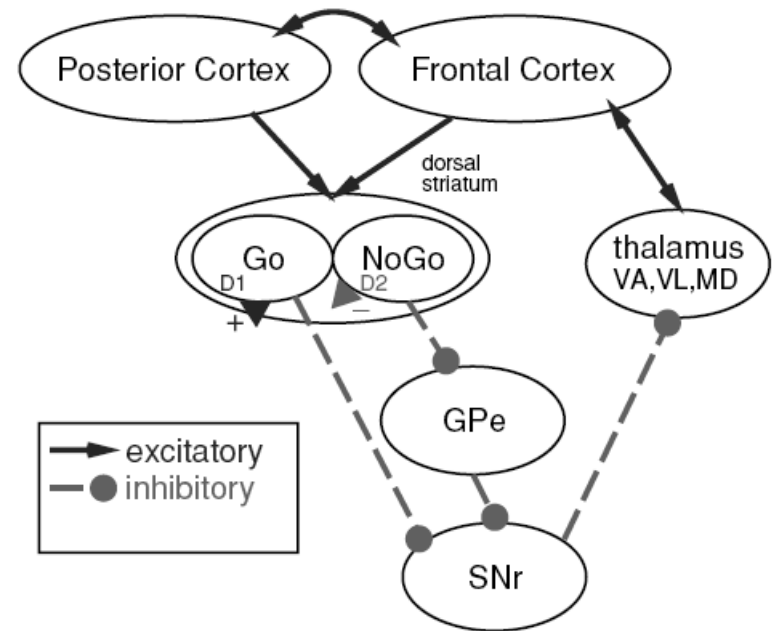
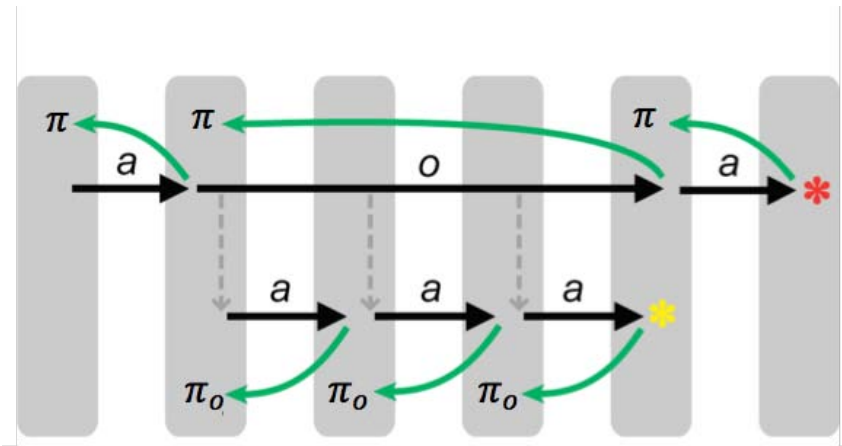


Miller & Cohen, *Ann. Rev. Neurosci*, 2001

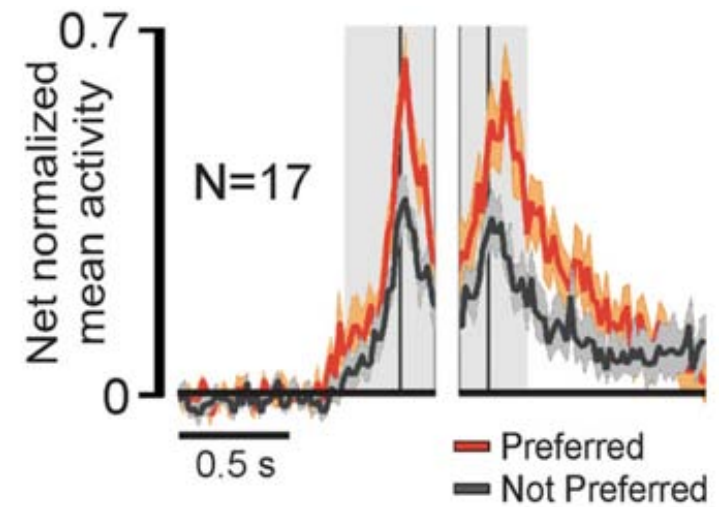
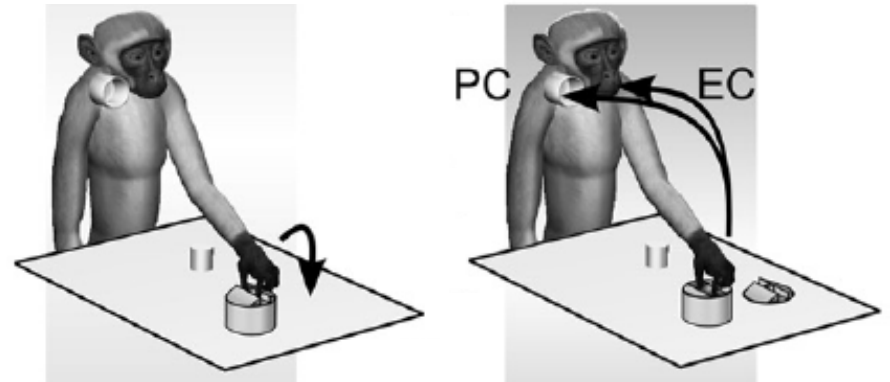
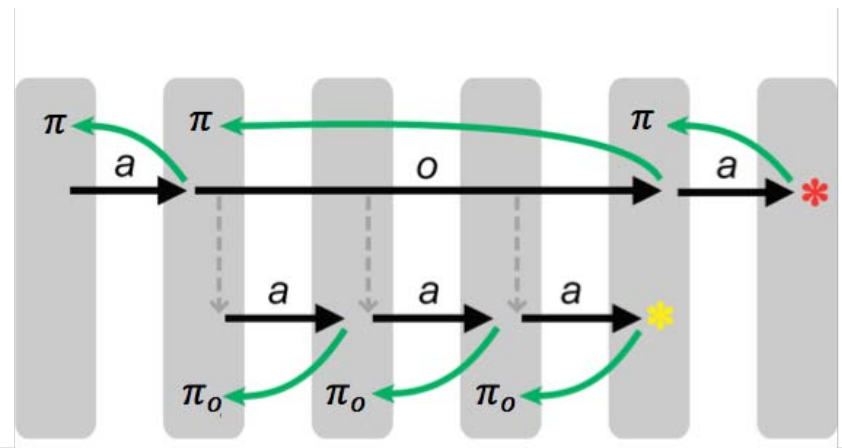


From Badre, *TICS*, 2008

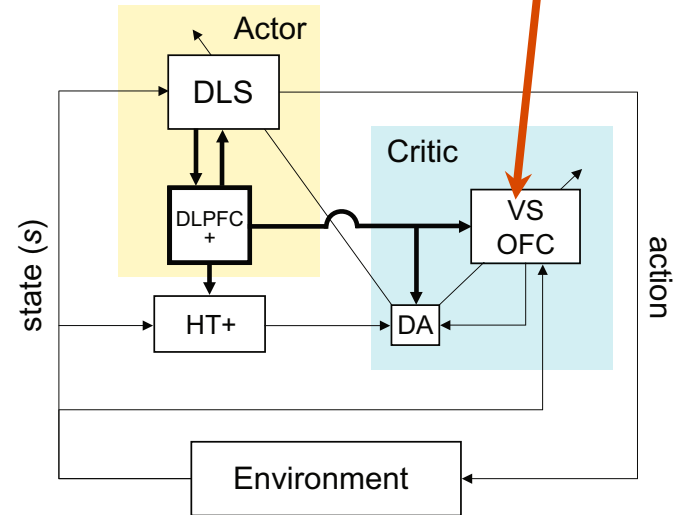
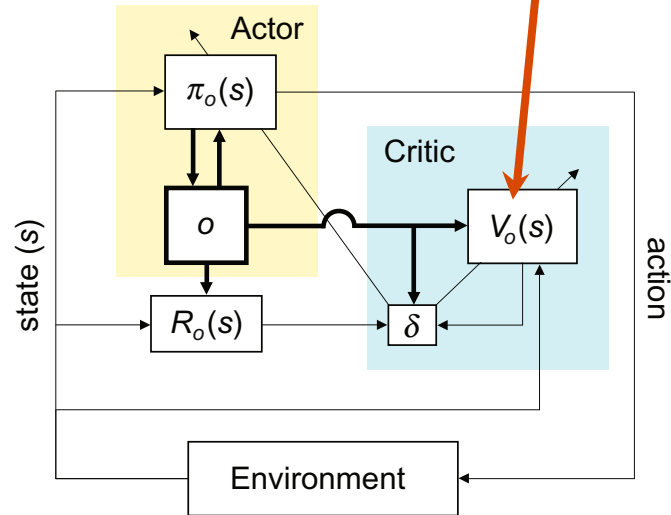
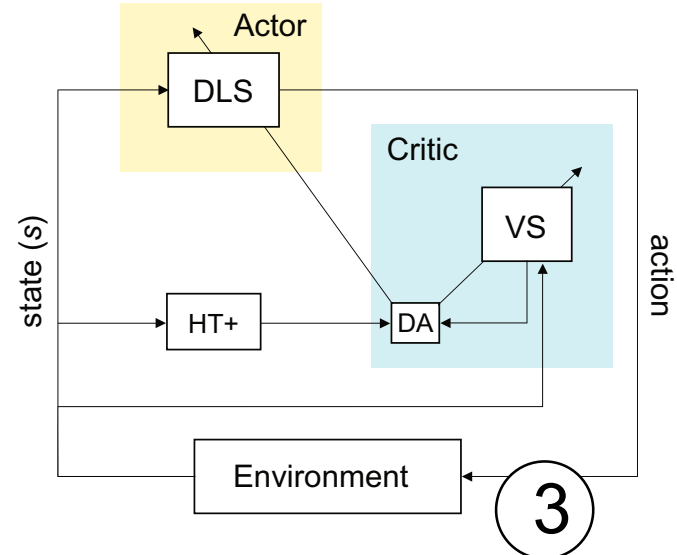
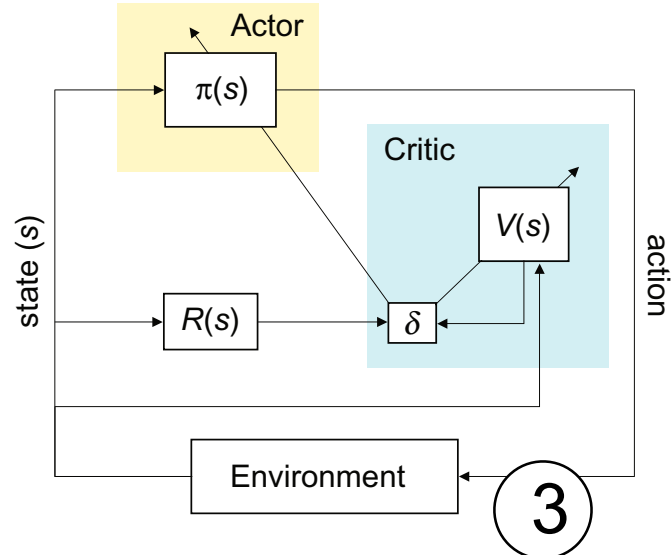




O'Reilly & Frank, *Neural Computation*, 2006

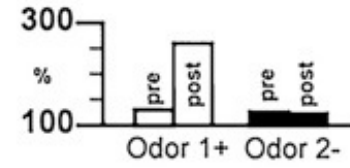
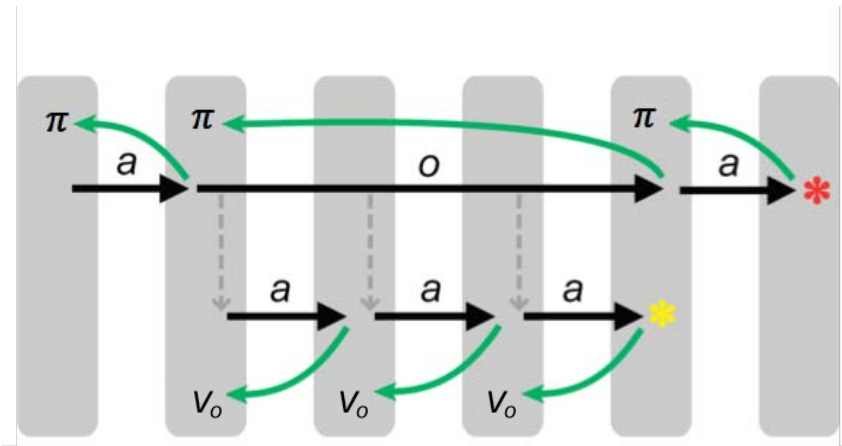


Bonini et al., *J. Neurosci.*, 2011



3

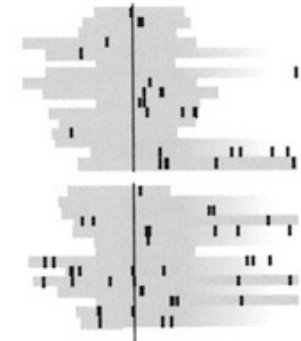
3



Odor
1

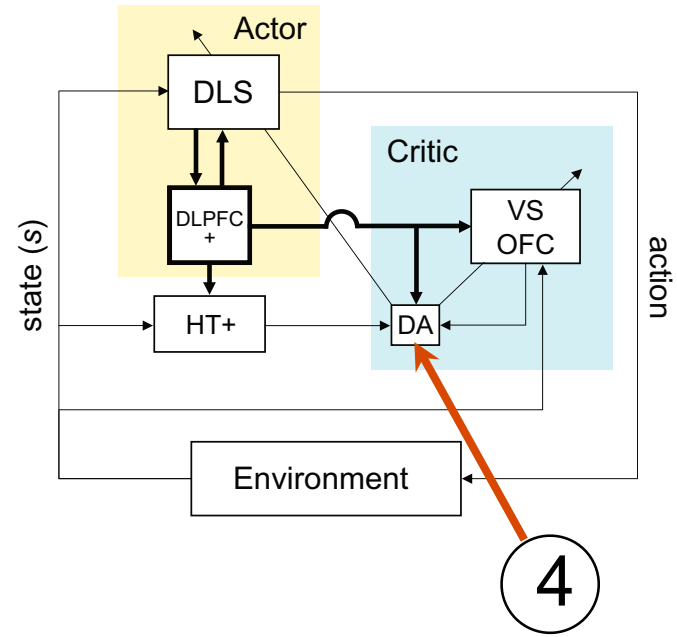
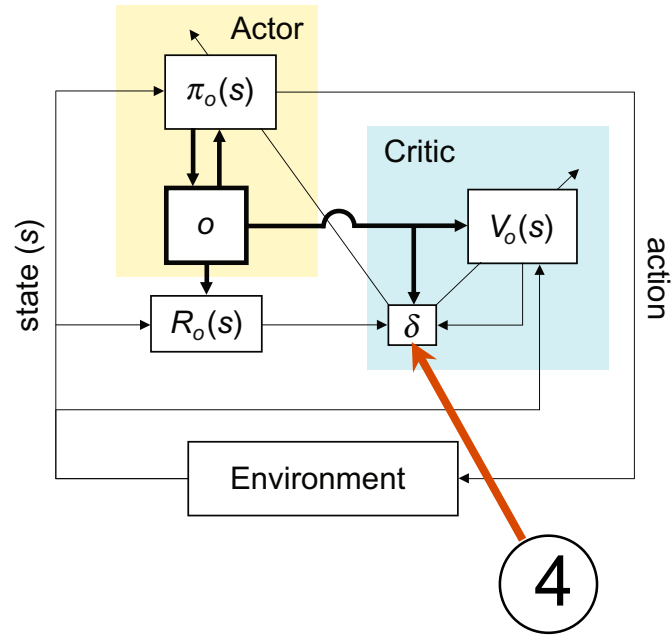
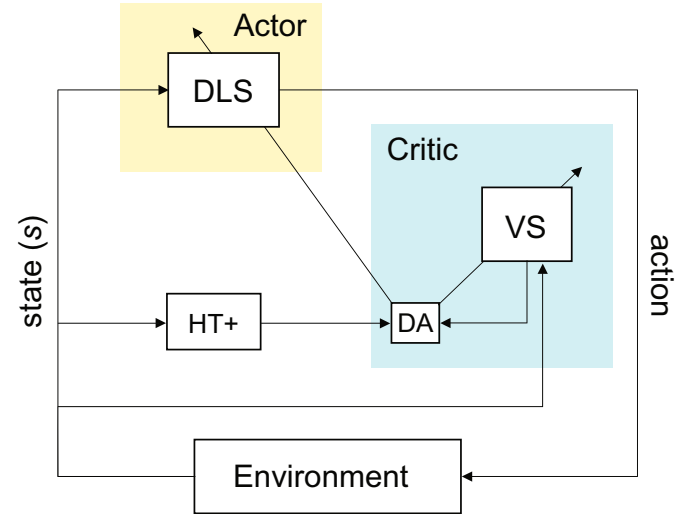
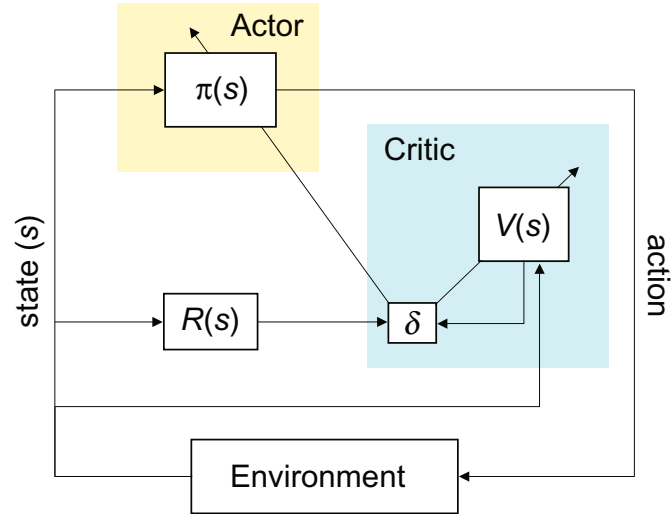


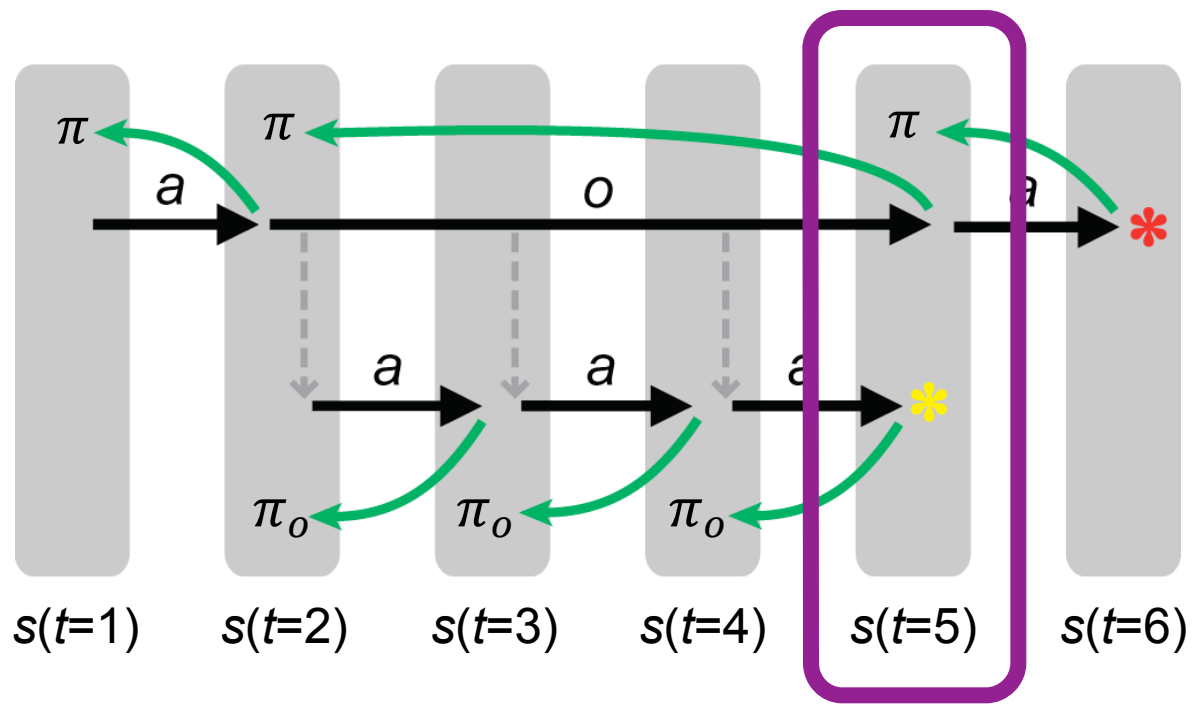
Odor
2



Odor Offset

Schoenbaum, et al. *J Neurosci.* 1999





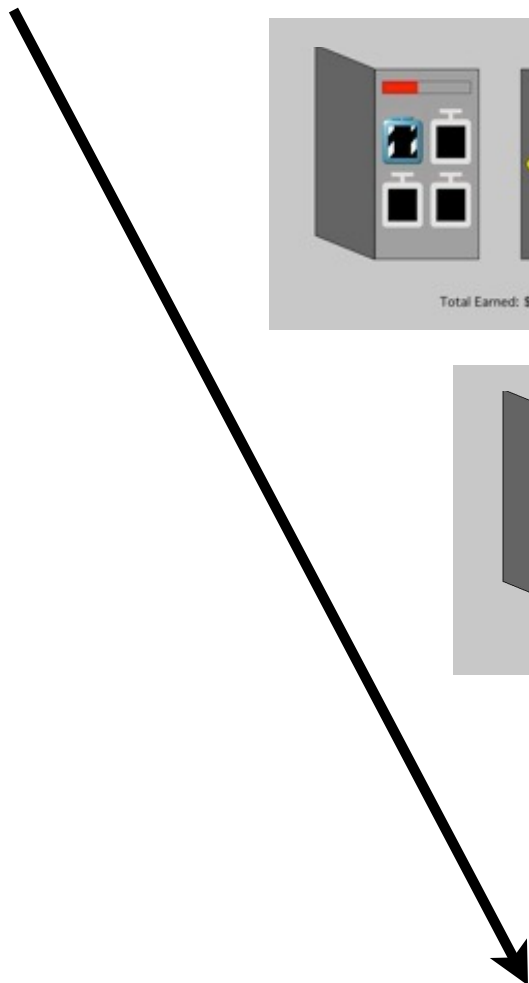
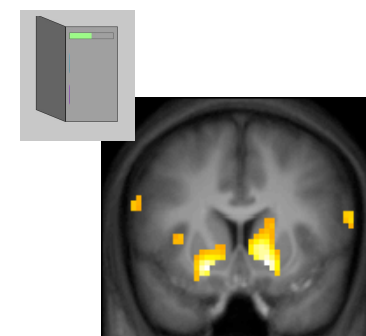
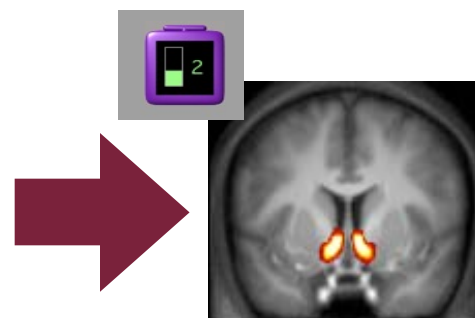
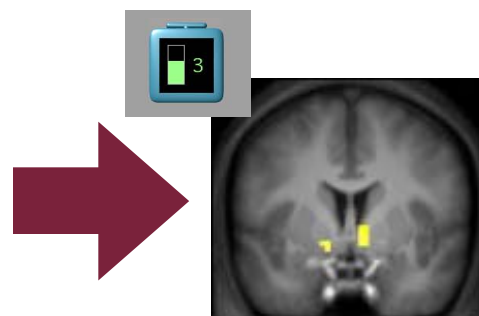
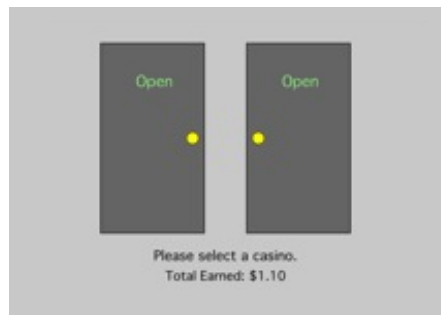


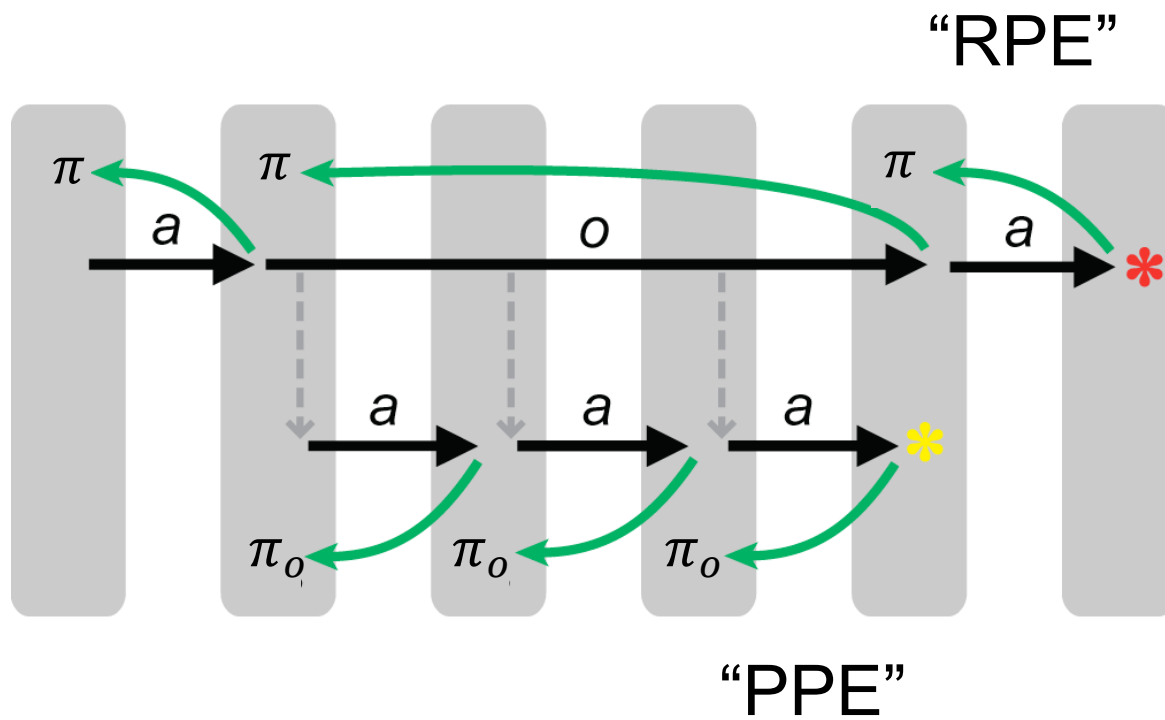
Carlos Diuk





Carlos Diuk



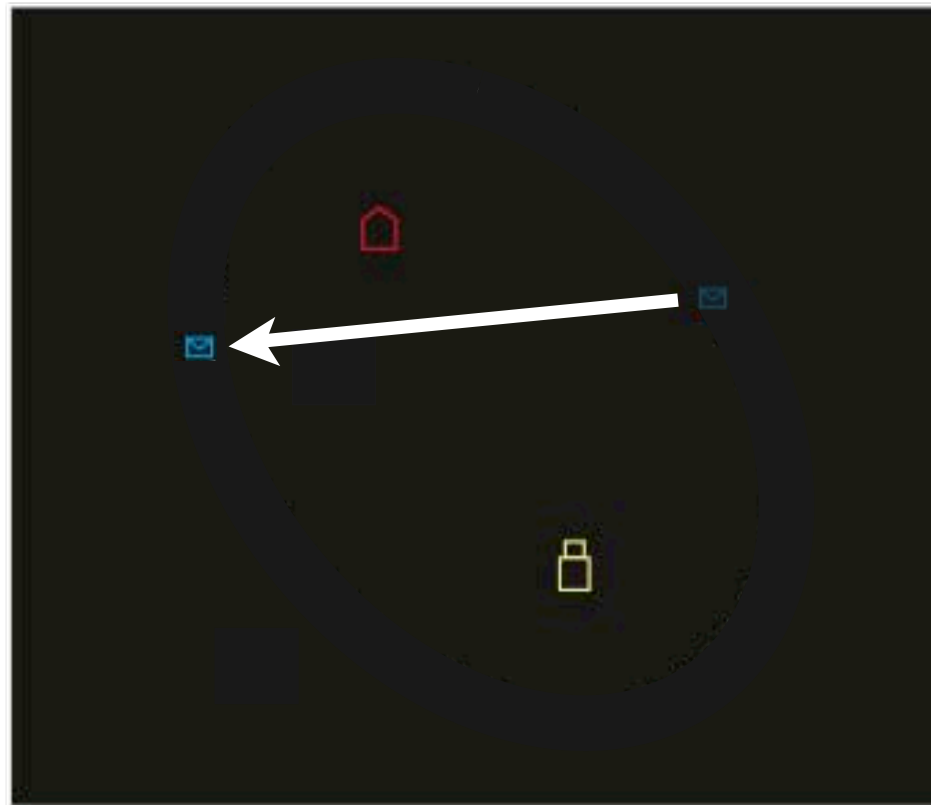




Jose Fernandes



Alec Solway

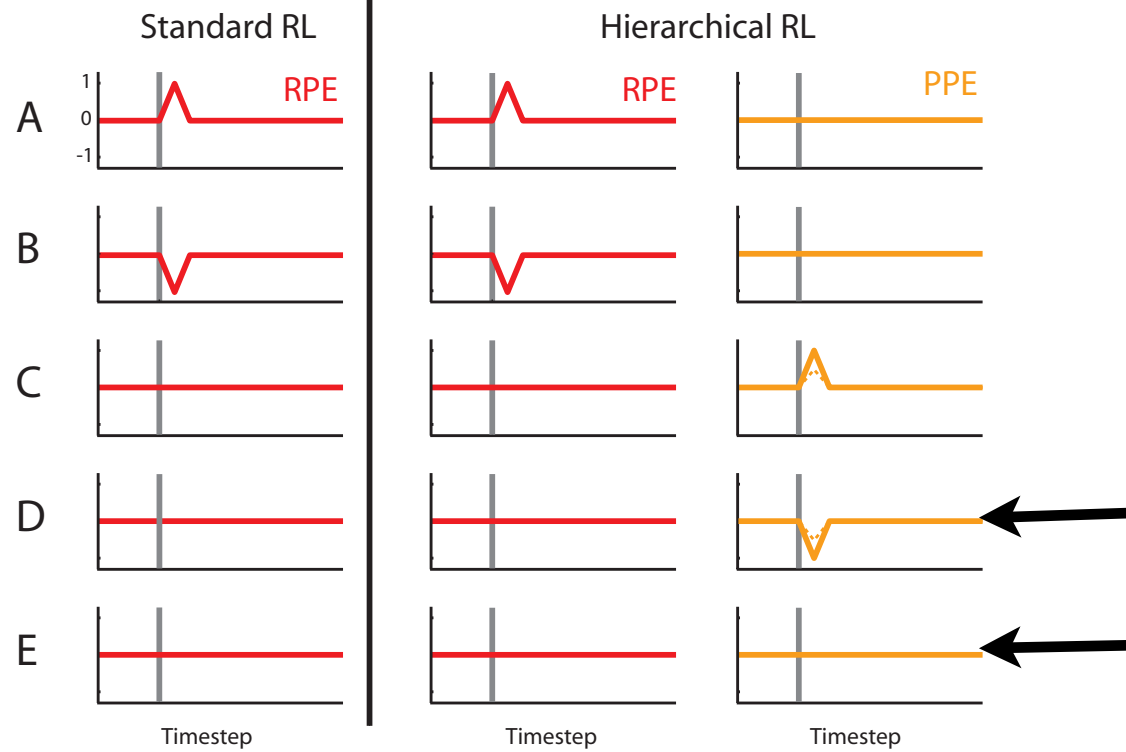
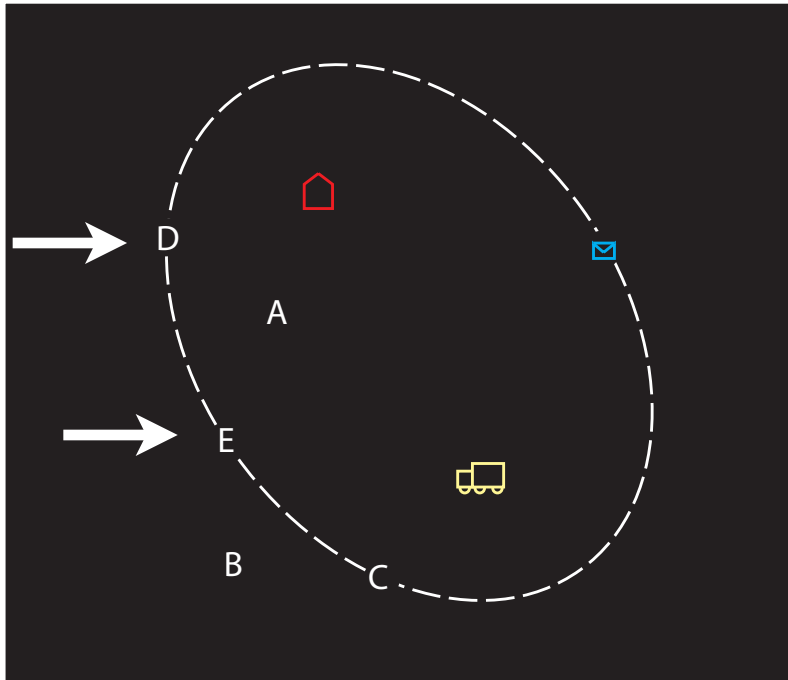




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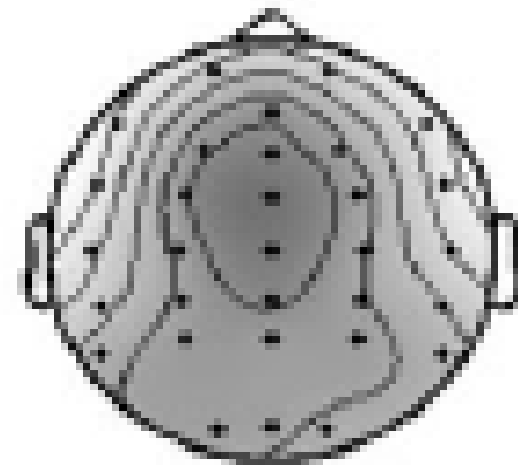
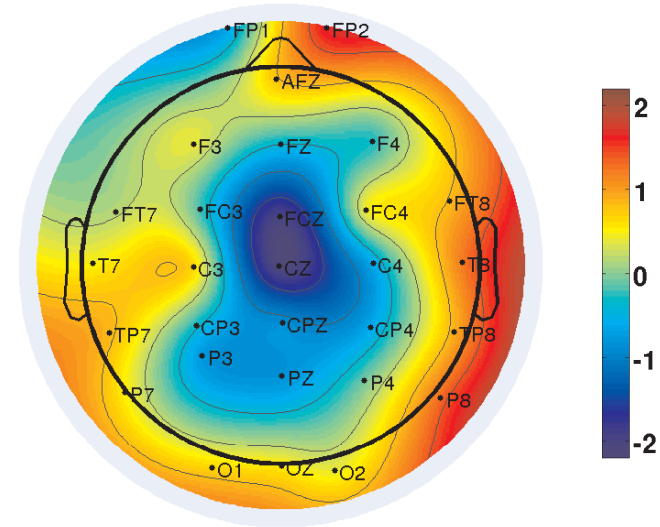
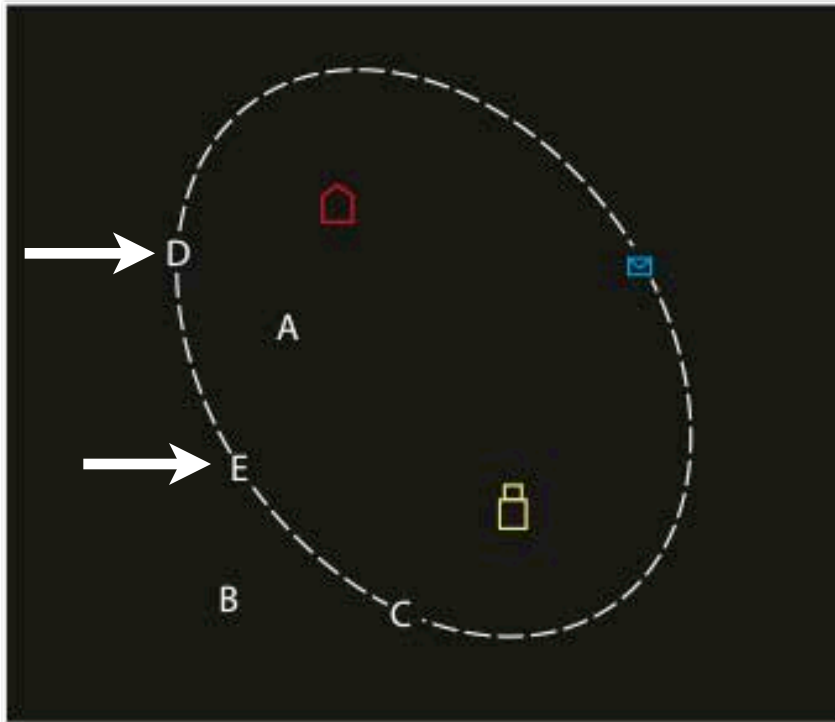




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From Yeung, et al., 2005

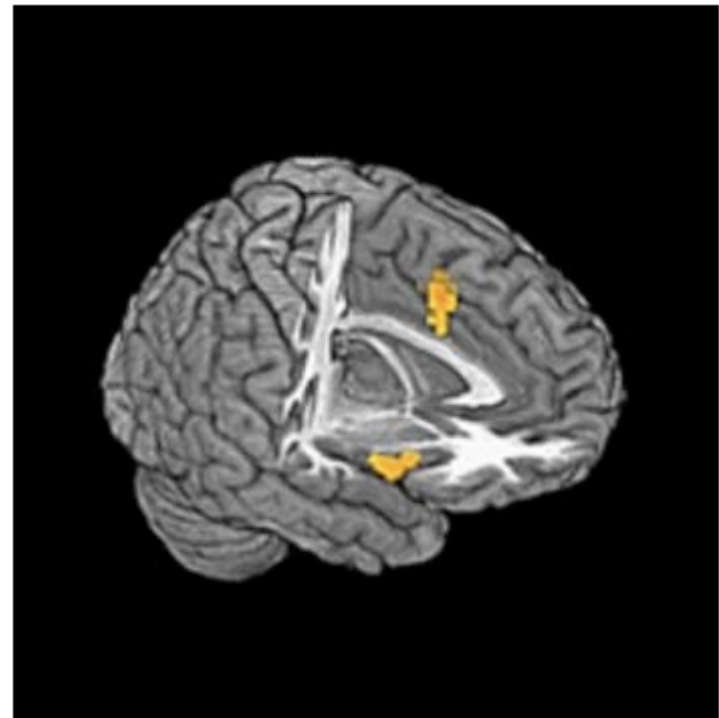
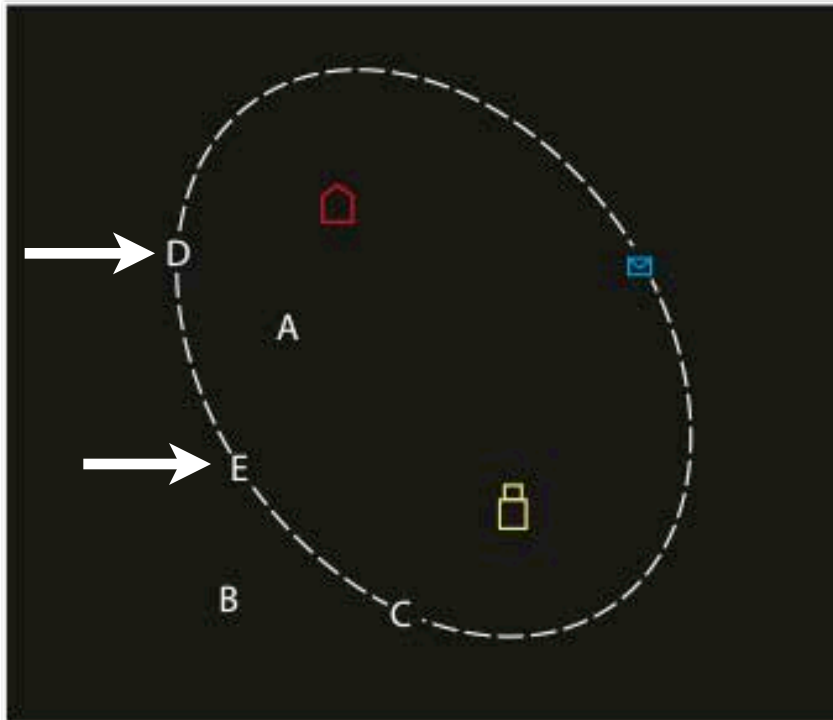
Ribas-Fernandes et al., *Neuron*, 2011

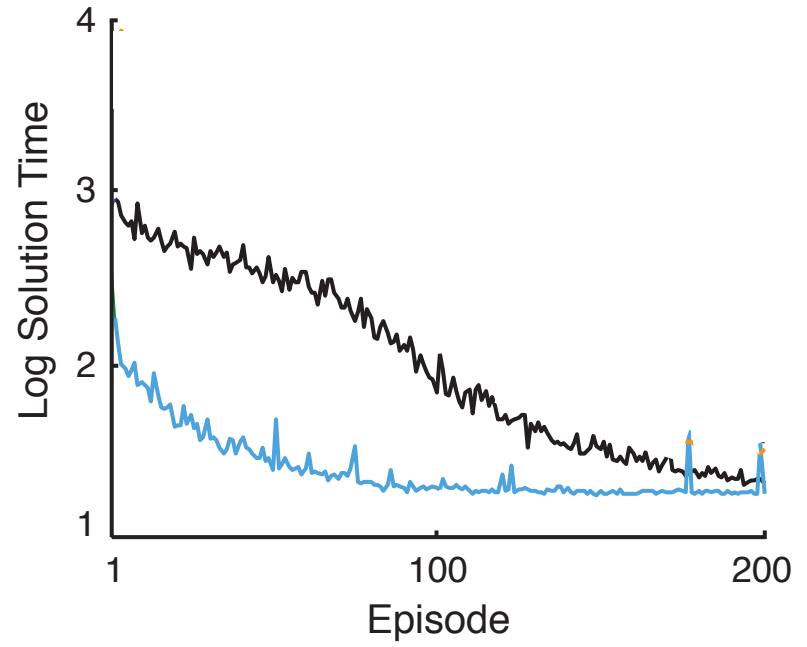
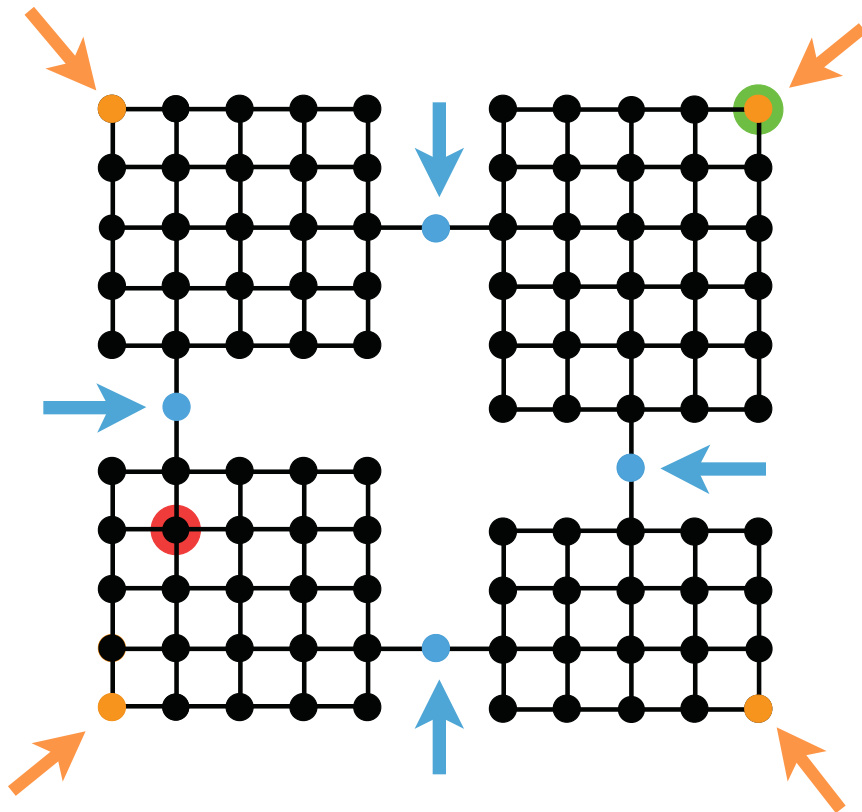


Jose Fernandes



Alec Solway





The Burden of Abstraction



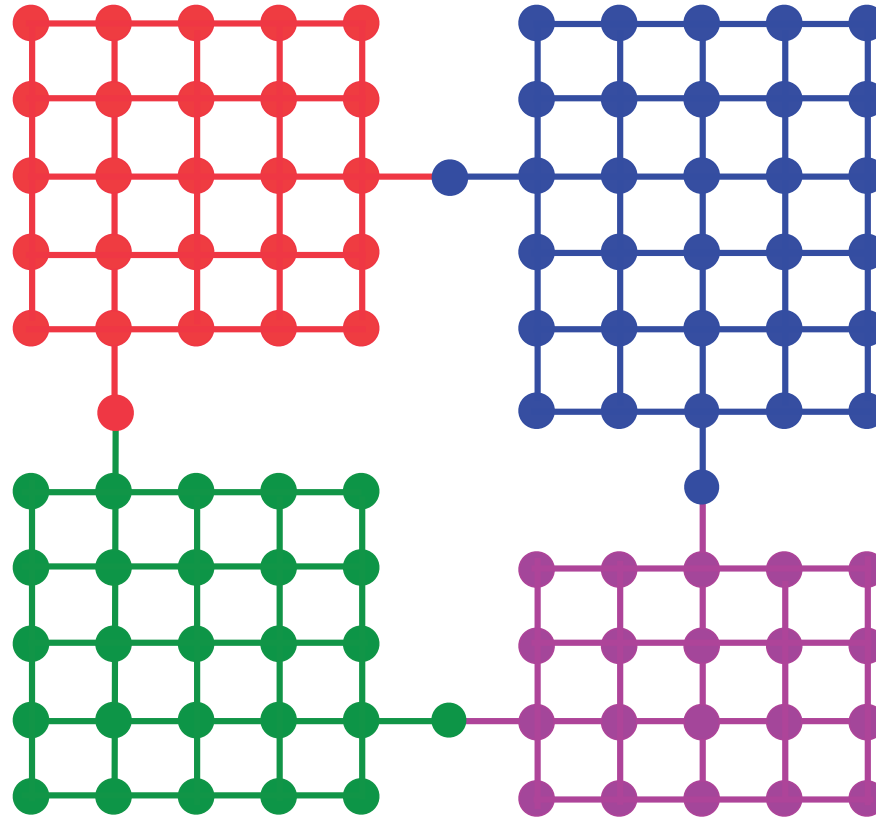
1. What should be learned?
2. Do people learn it?
3. How?



Alec Solway



Carlos Diuk

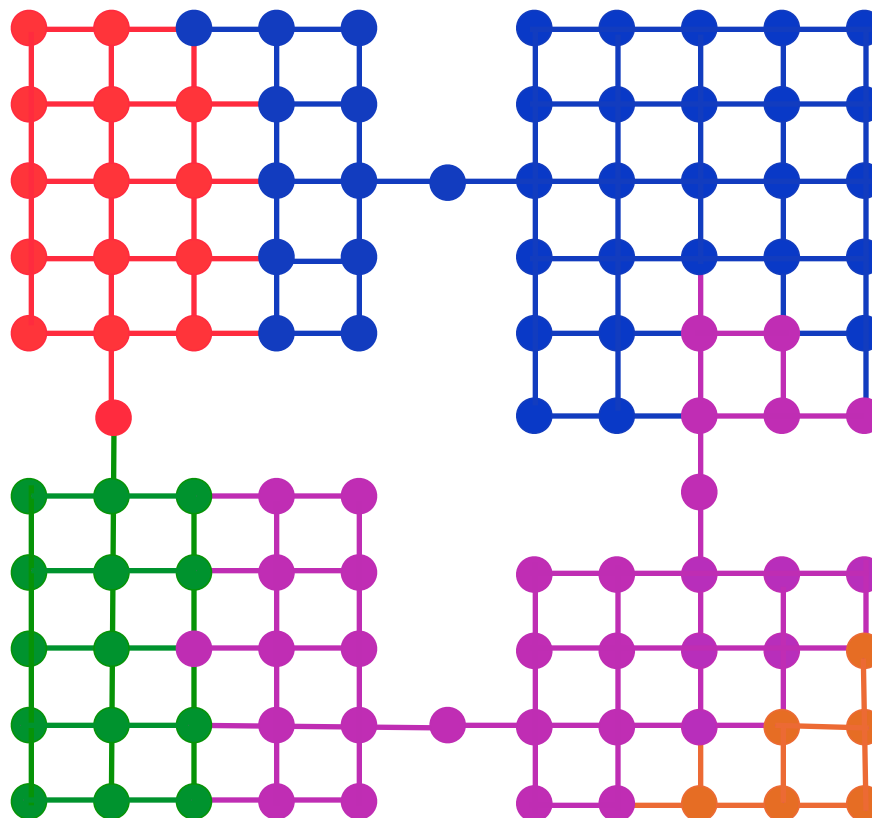




Alec Solway



Carlos Diuk

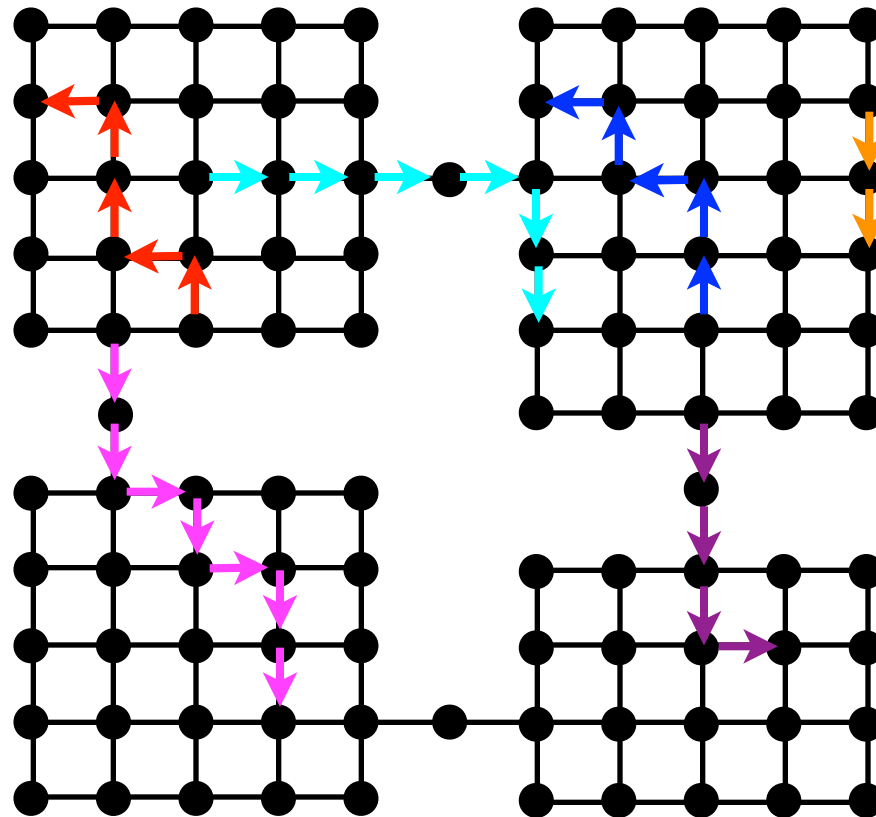




Alec Solway



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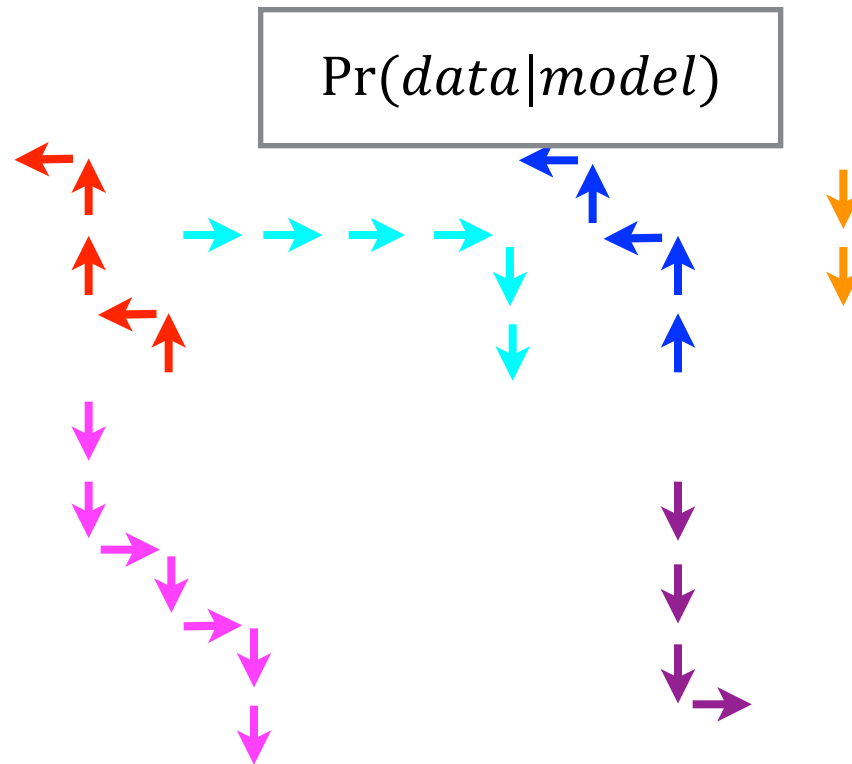
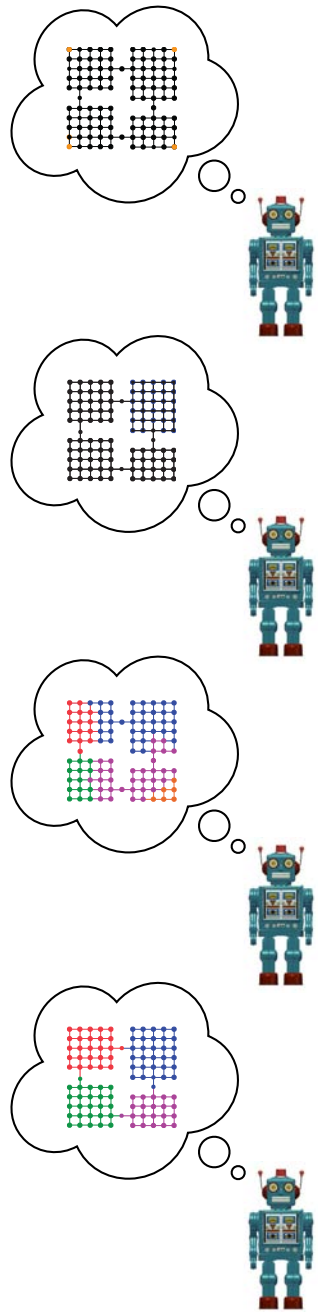


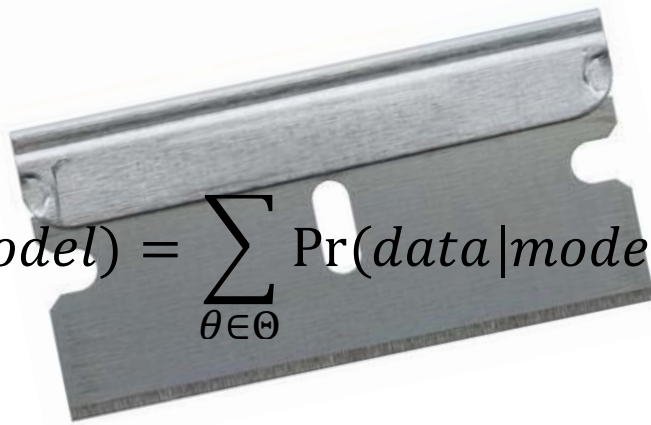
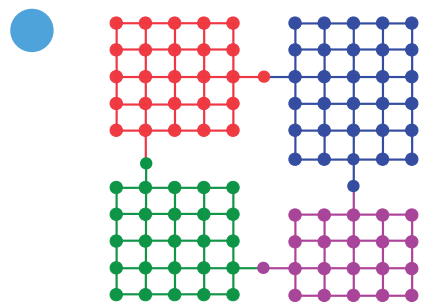
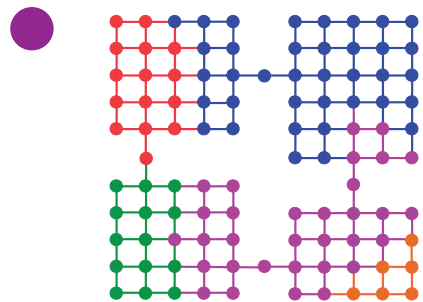
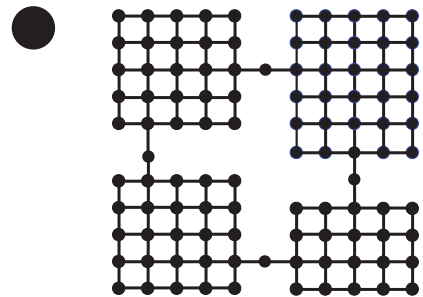
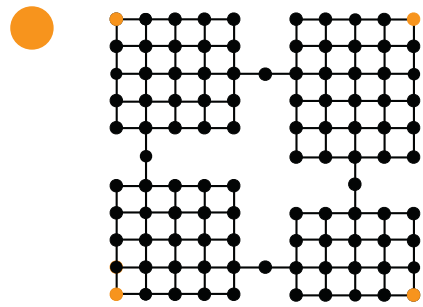


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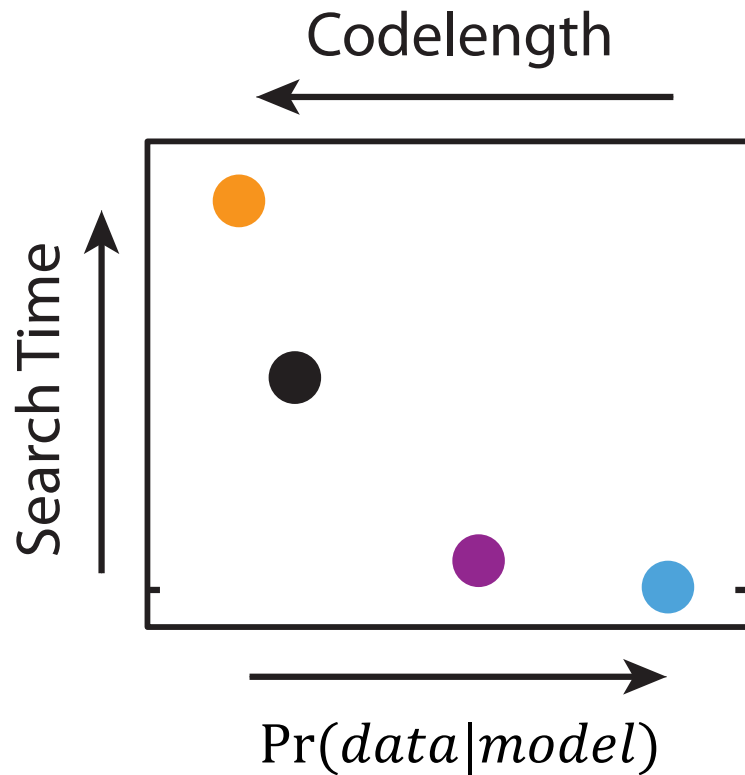


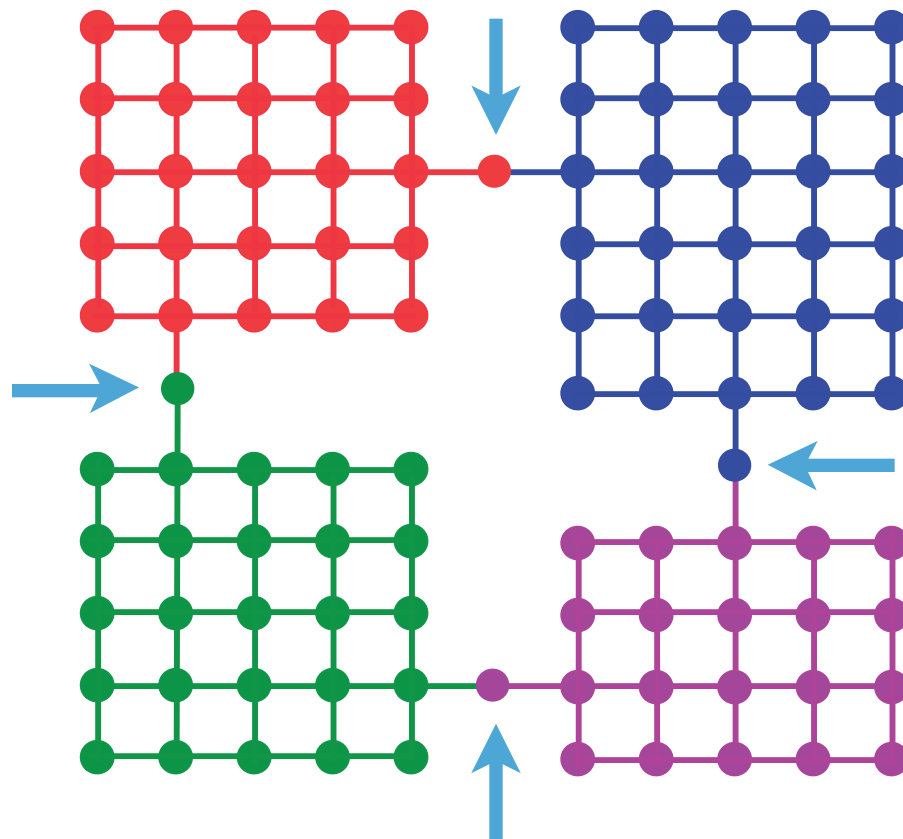
Carlos Diuk

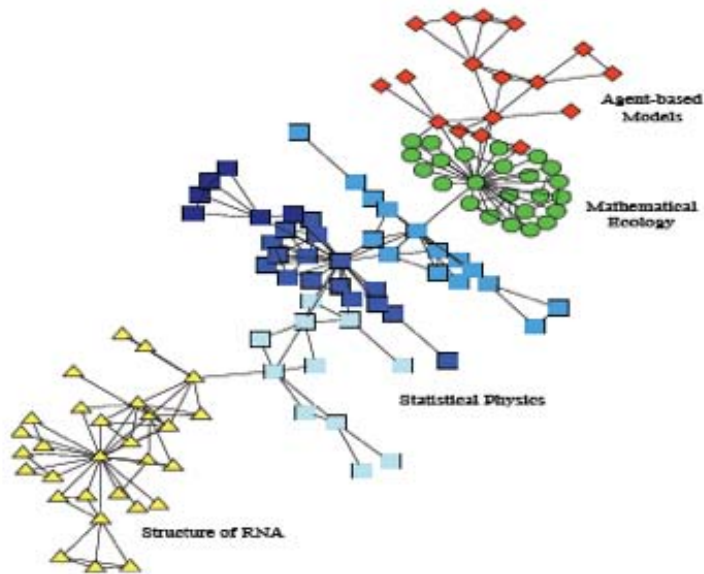
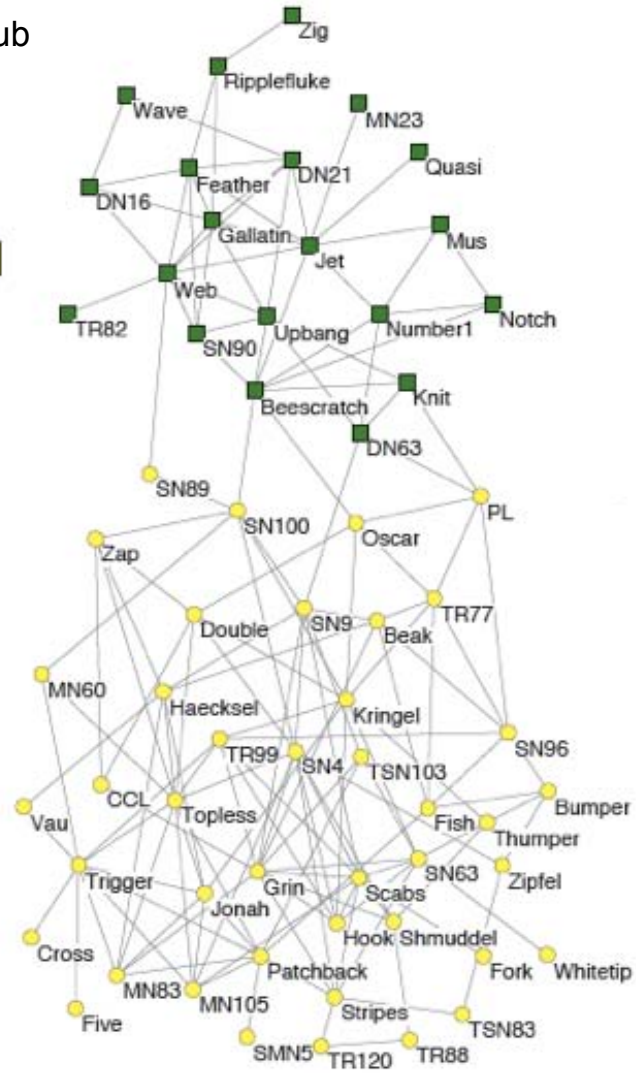
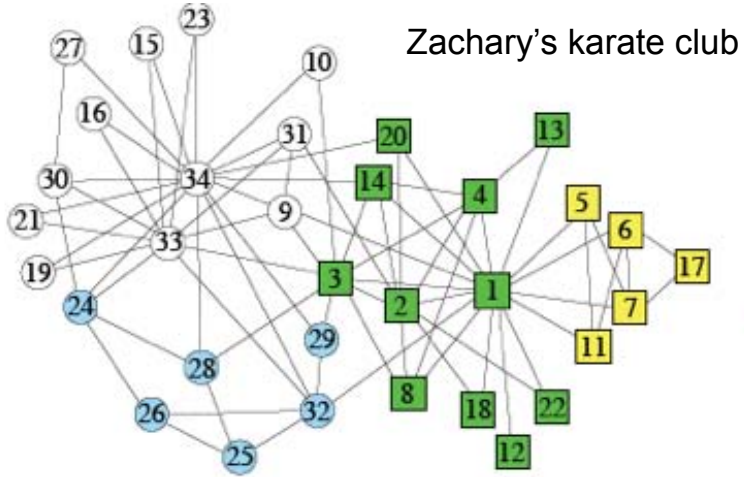




$$\Pr(data|model) = \sum_{\theta \in \Theta} \Pr(data|model, \theta) \Pr(\theta|model)$$

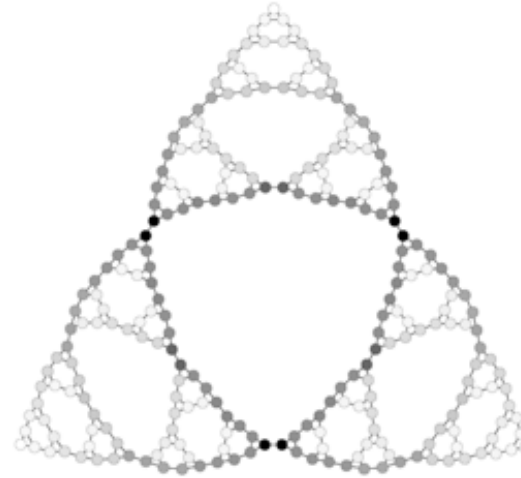
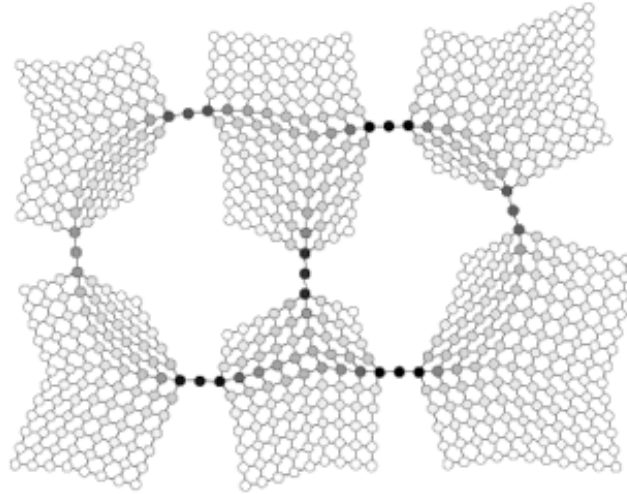
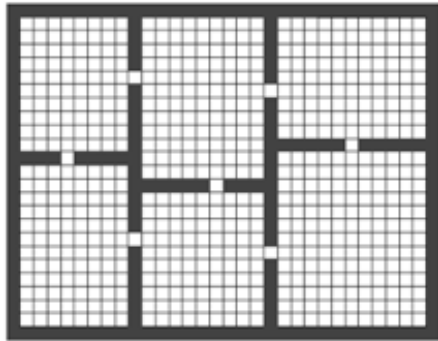






Santa Fe Institute collaborations

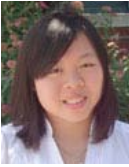
Lusseau's bottlenose dolphins



1. What should be learned?
2. Do people learn it?
3. How?



Carlos Diuk

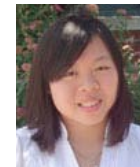


DebbieYee

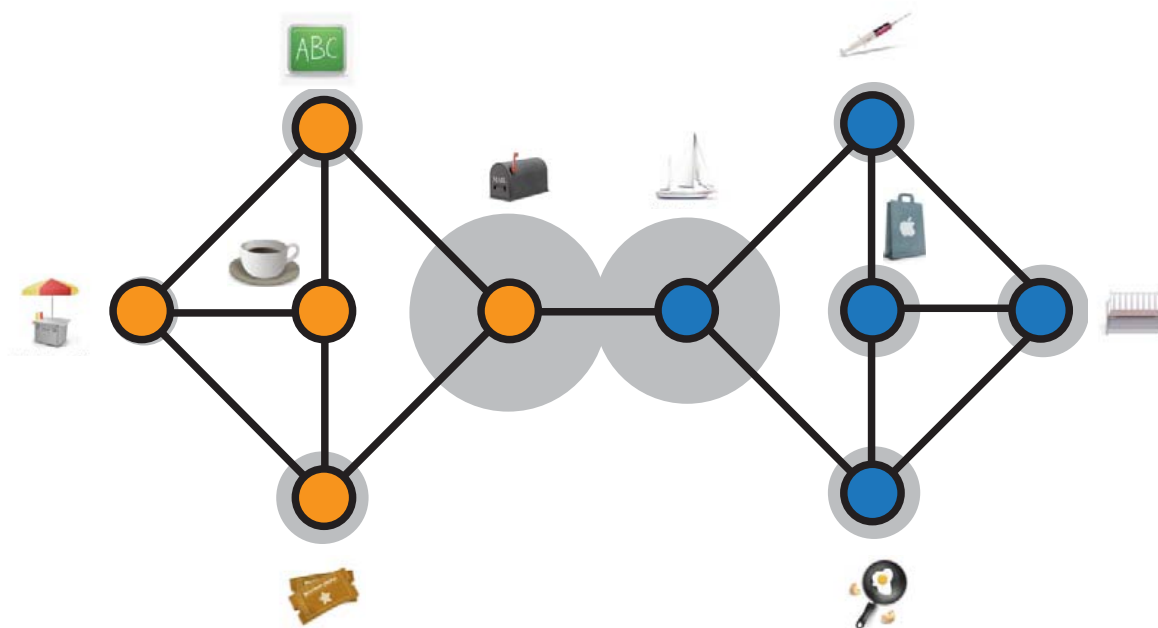




Carlos Diuk

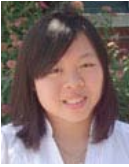


Debbie Yee
























Carlos Diuk



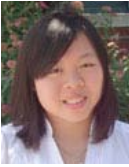
DebbieYee

Click on locations that are along the path between start and goal IN ANY ORDER.

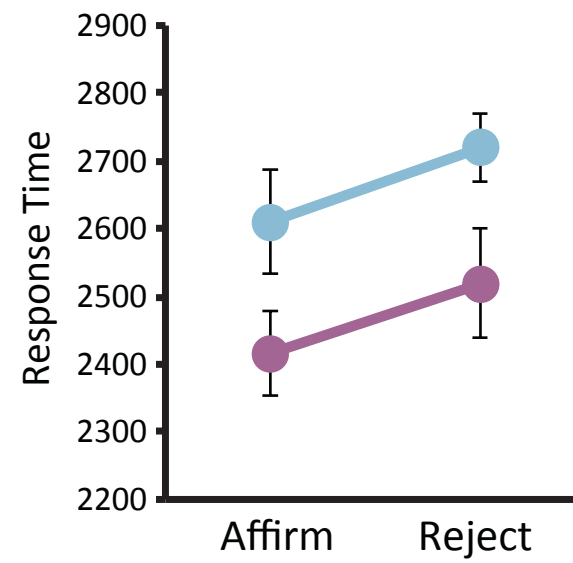
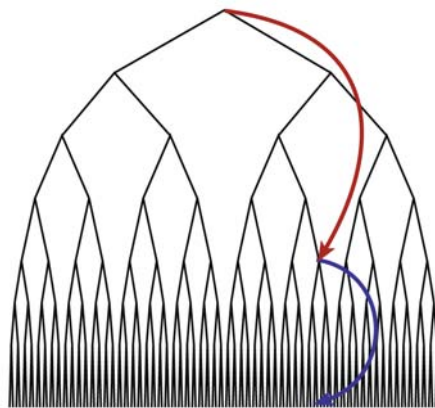
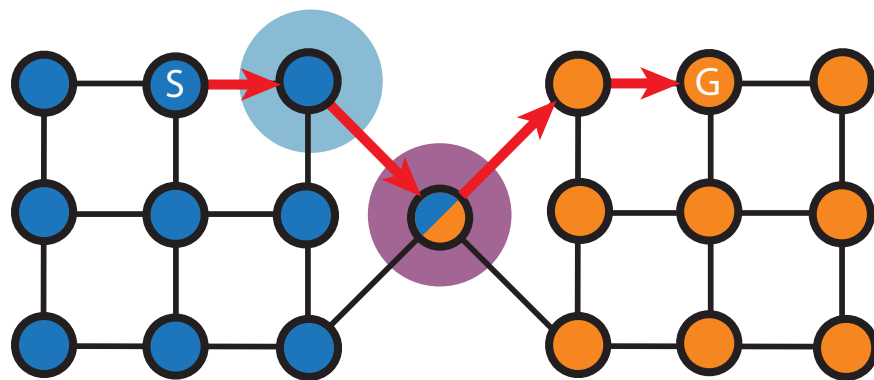
 Construction Site	 Airport	 Post Office	 Ice-cream Parlor	 Movie Theater
 Bakery	 Library	 Diner	 Park	 Veterinary
 Beach	 City Docks	 Hot Dog Stand	 Computer Store	 Coffee Shop
 Hospital	 Amusement Park	 School	 Bus Station	



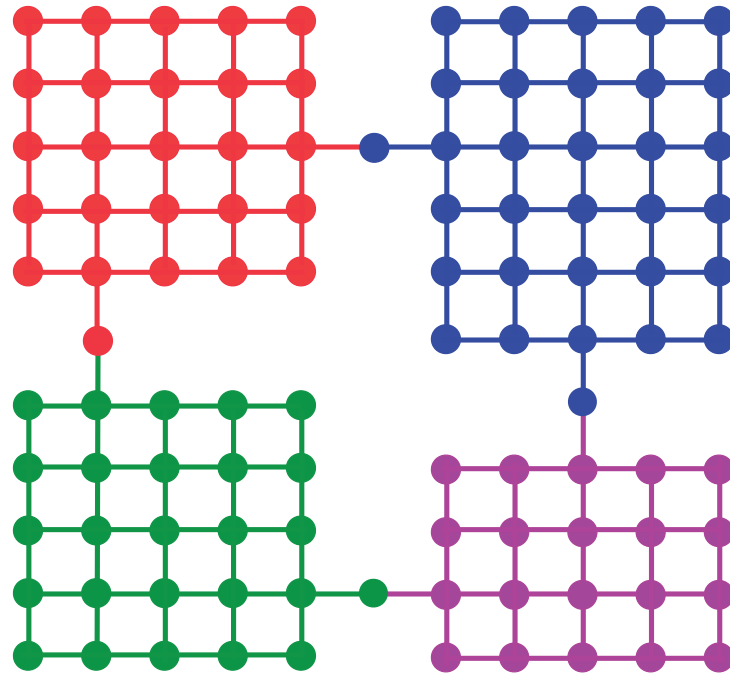
Carlos Diuk



Debbie Yee



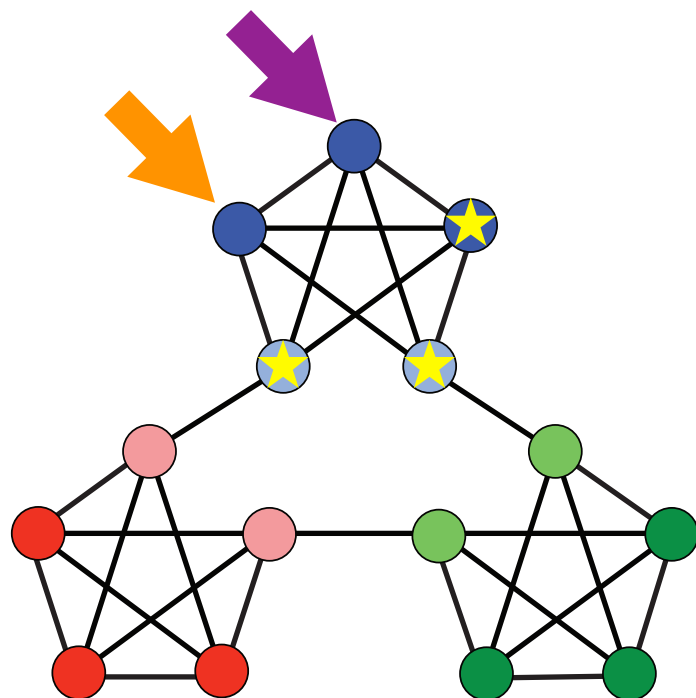
1. What should be learned?
2. Do people learn it?
3. How?

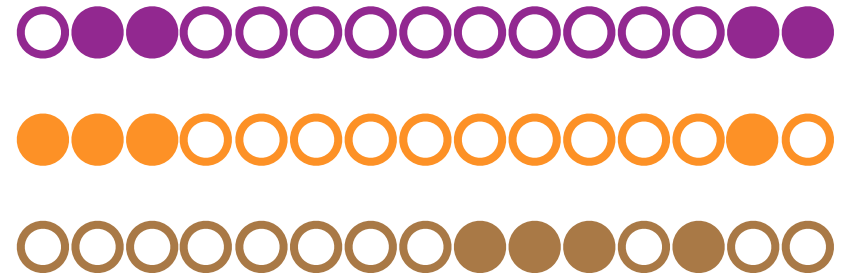
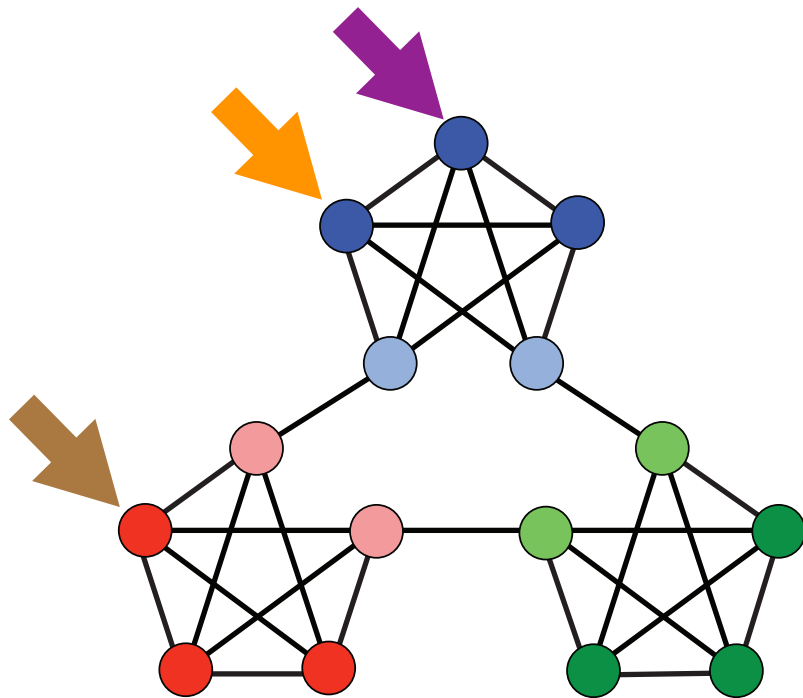


$$\Pr(data|model) = \sum_{\theta} \Pr(data|model, \theta) \Pr(\theta|model)$$

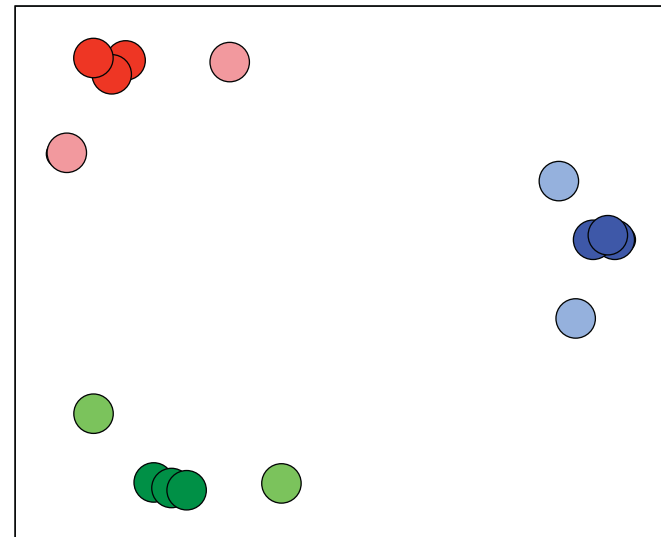
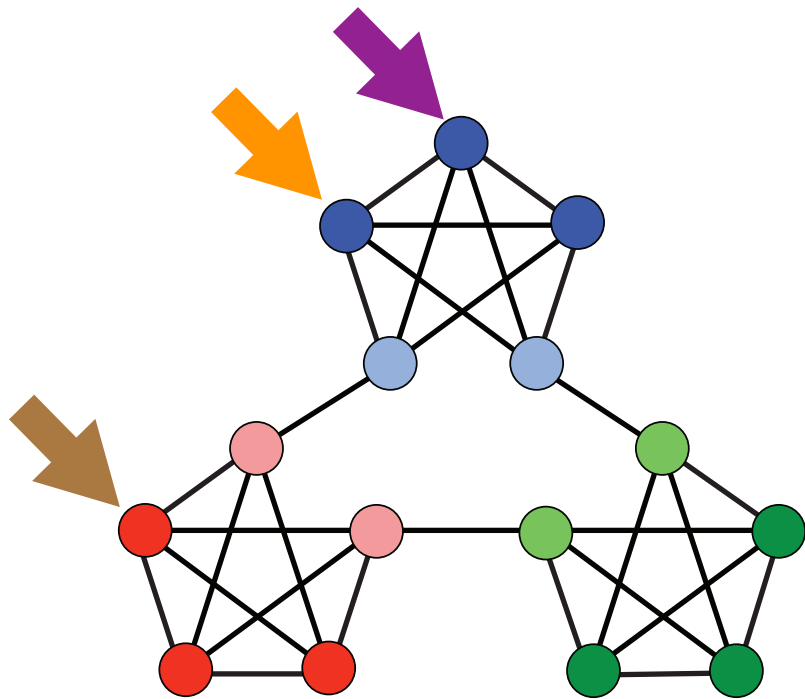


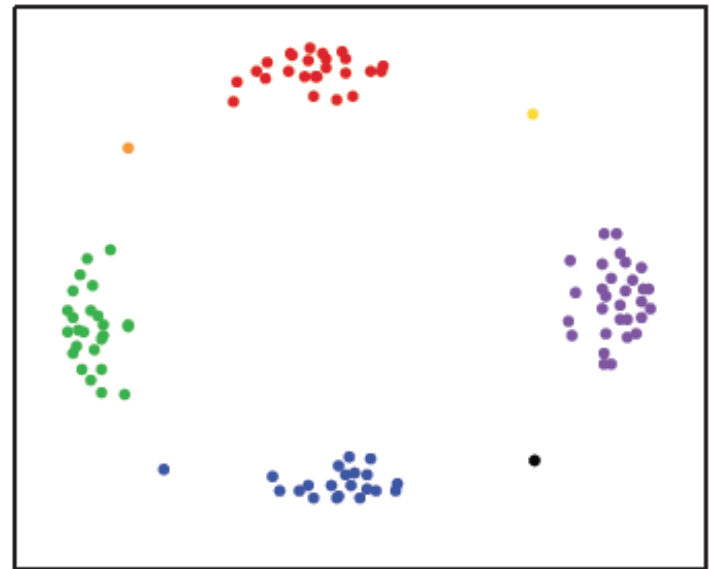
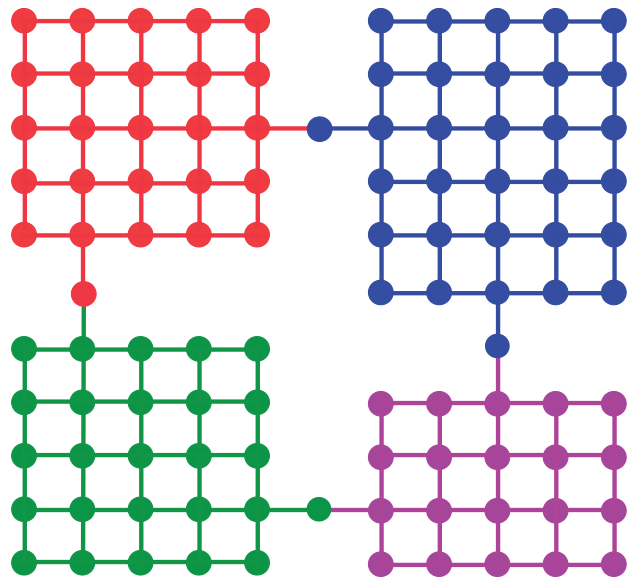
Anna Schapiro





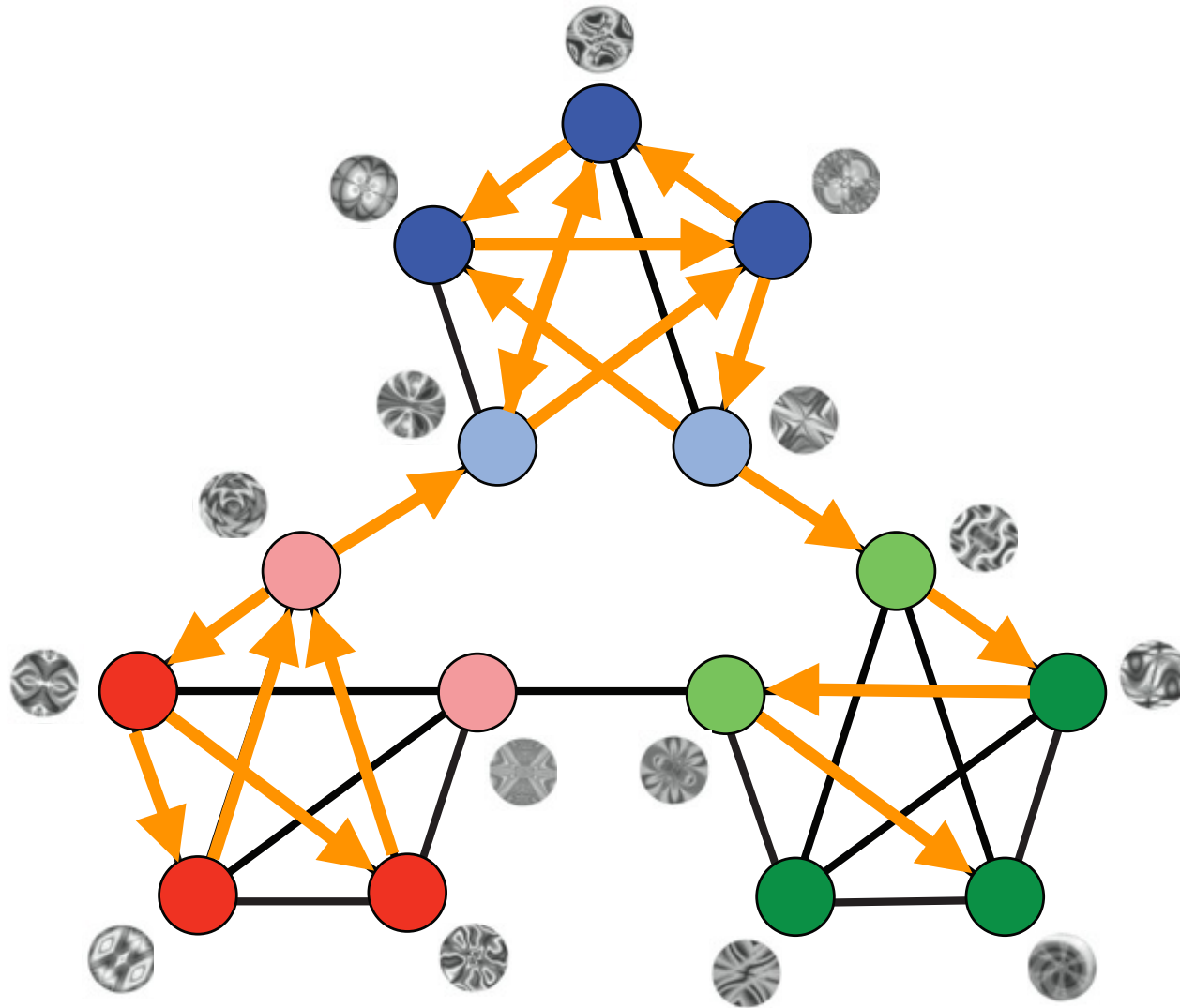
	↓	↓	↓
→	1.00	0.66	-0.36
→	0.66	1.00	-0.36
→	-0.36	-0.36	1.00

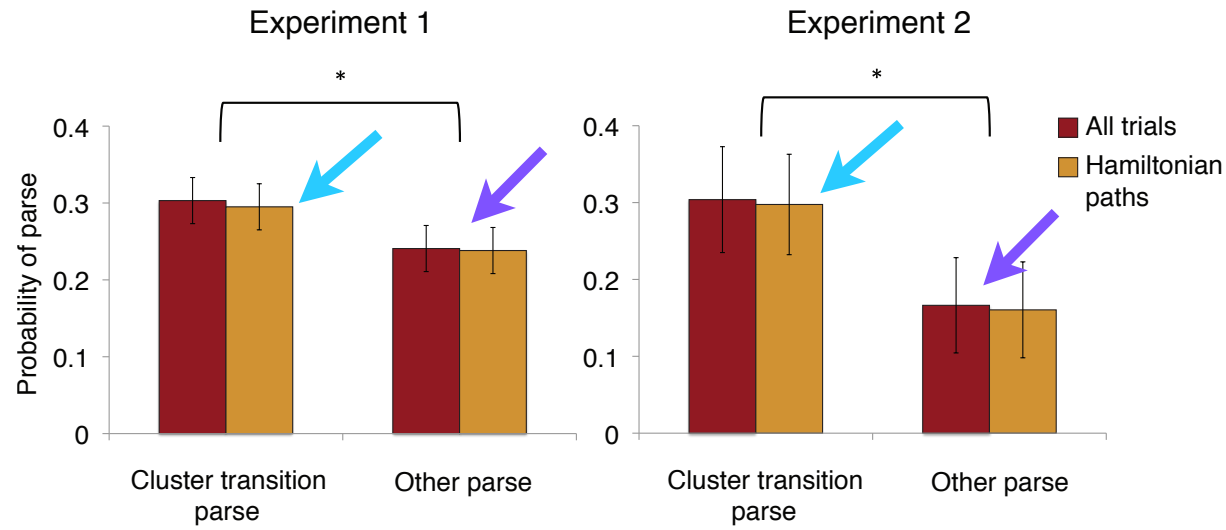
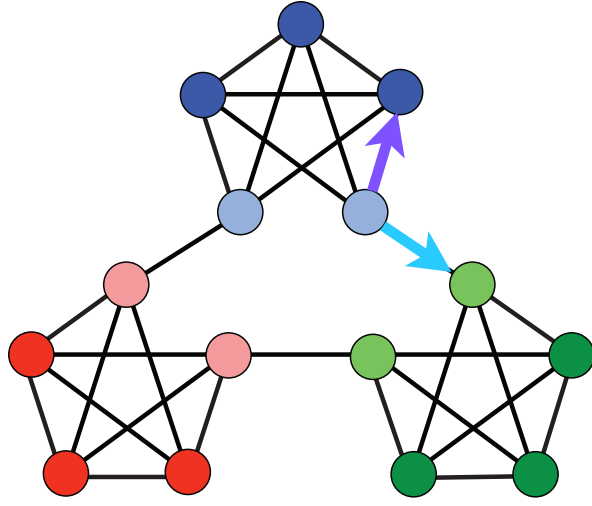


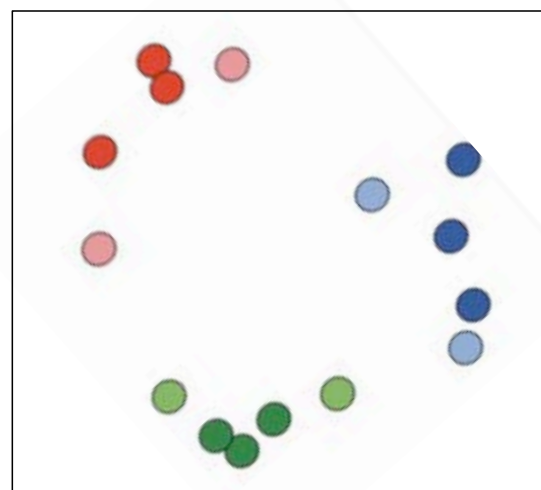
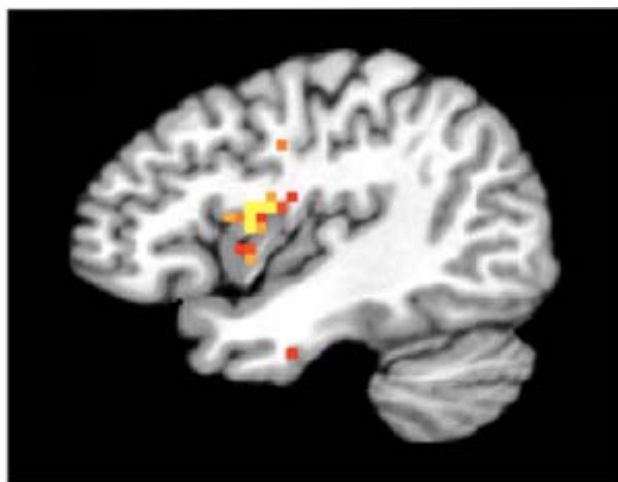
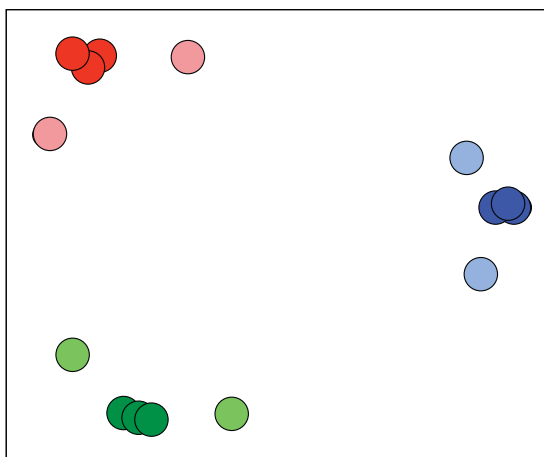




Time



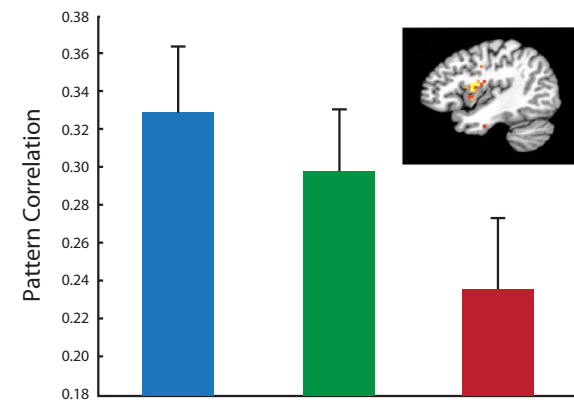
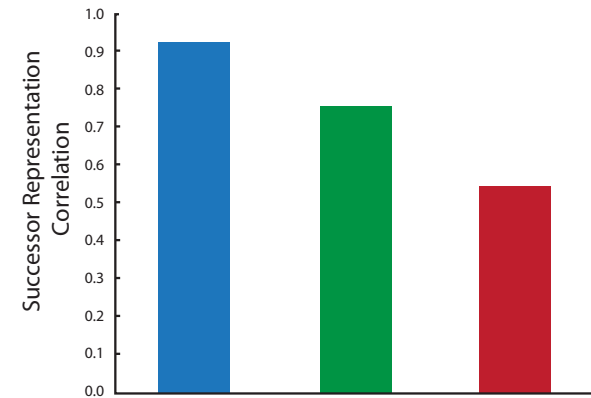
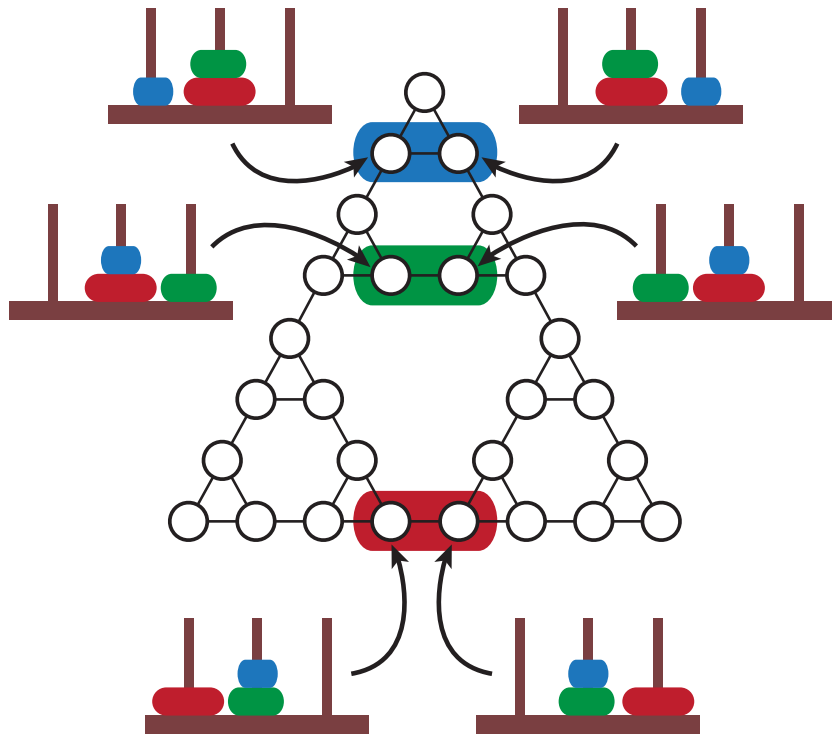




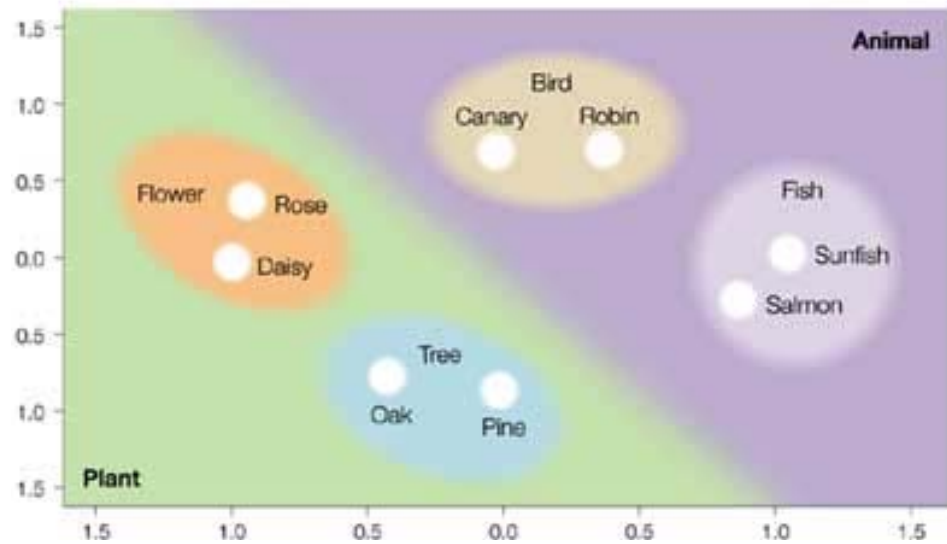
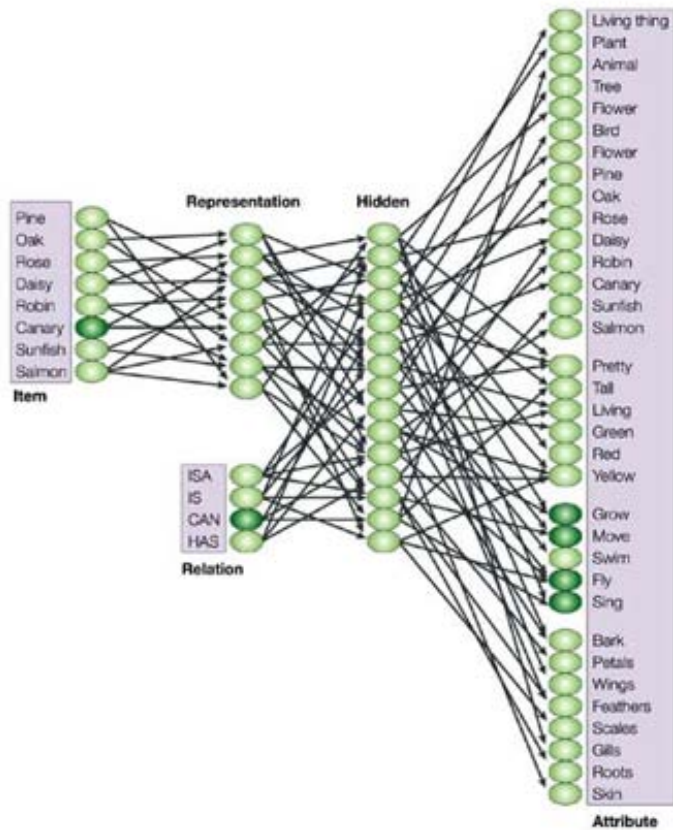
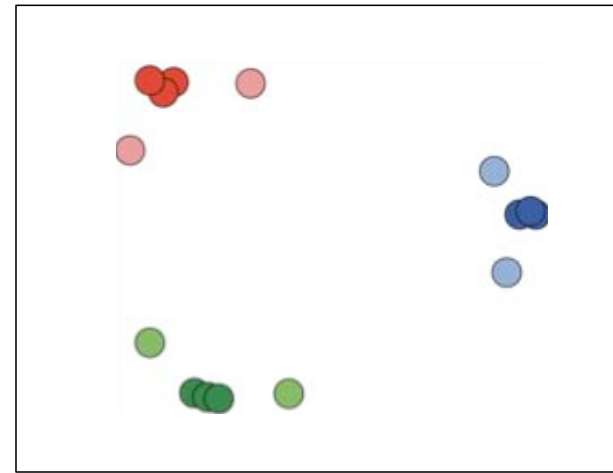
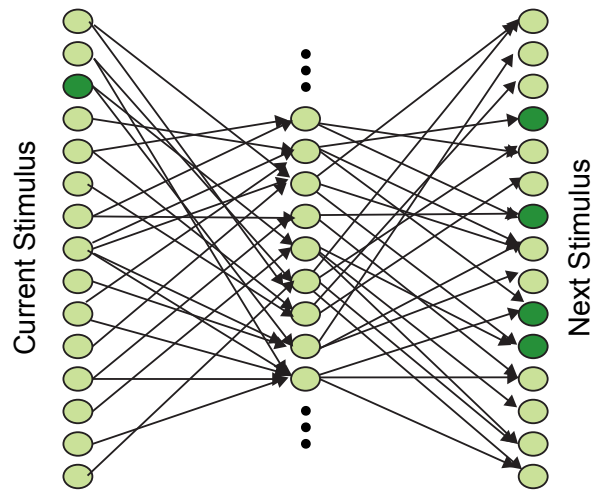
+ HC

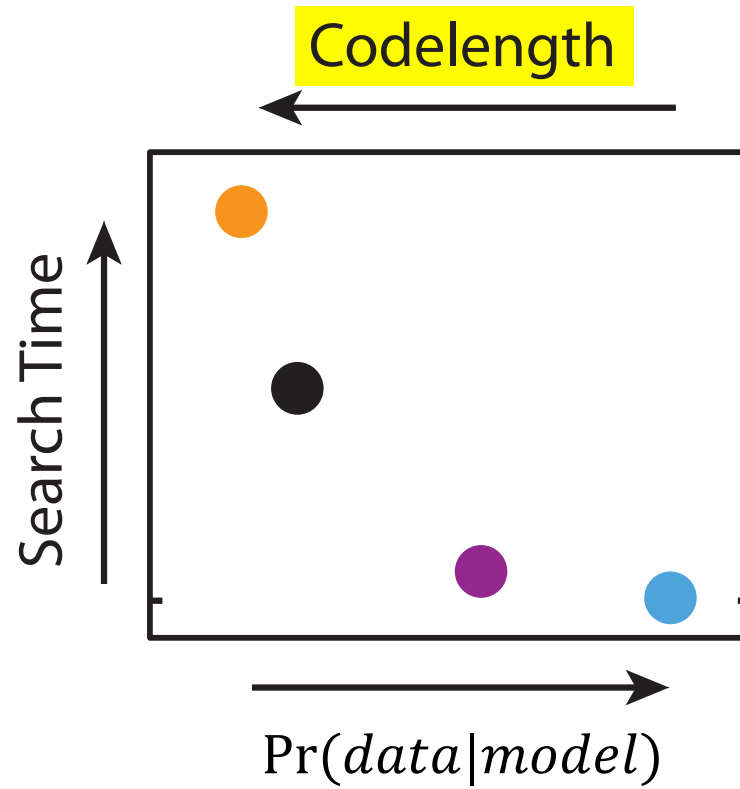
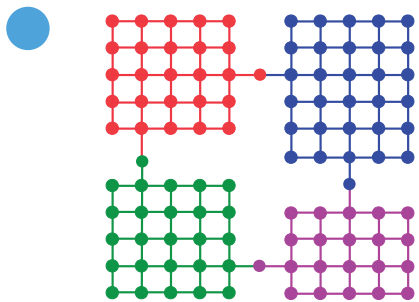
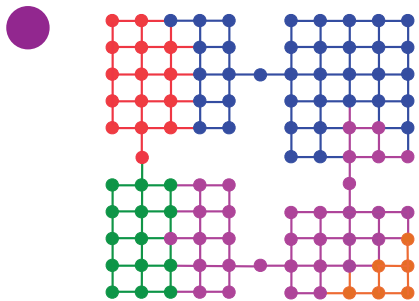
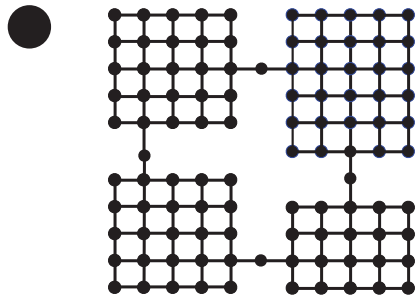
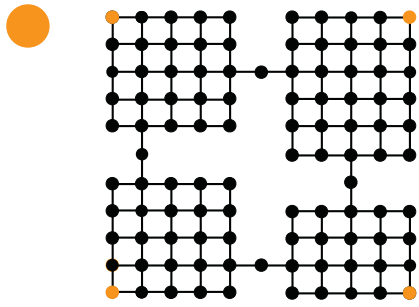


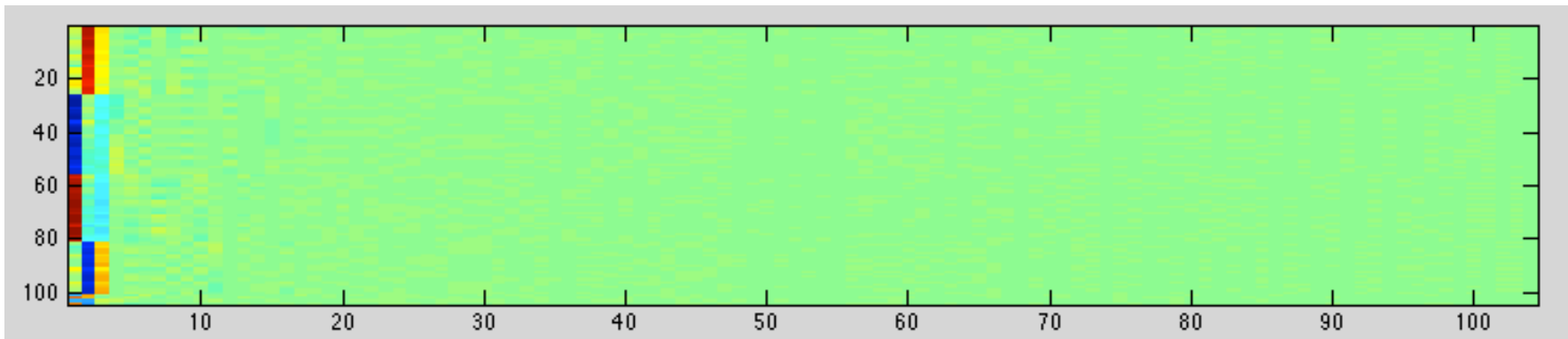
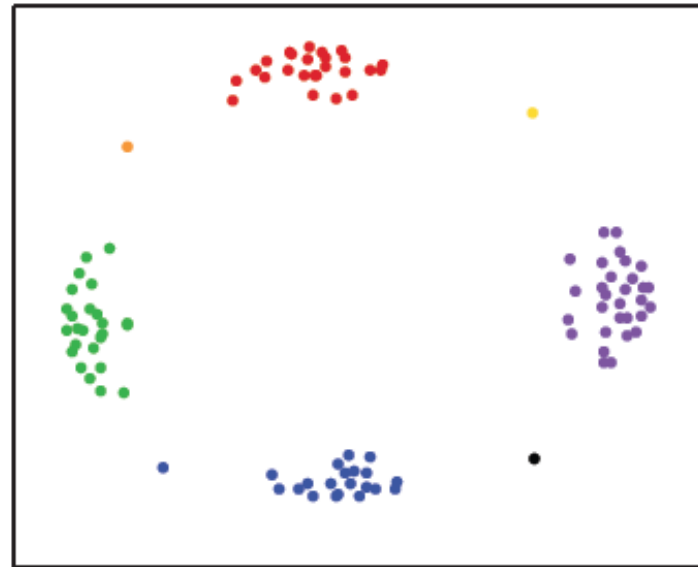
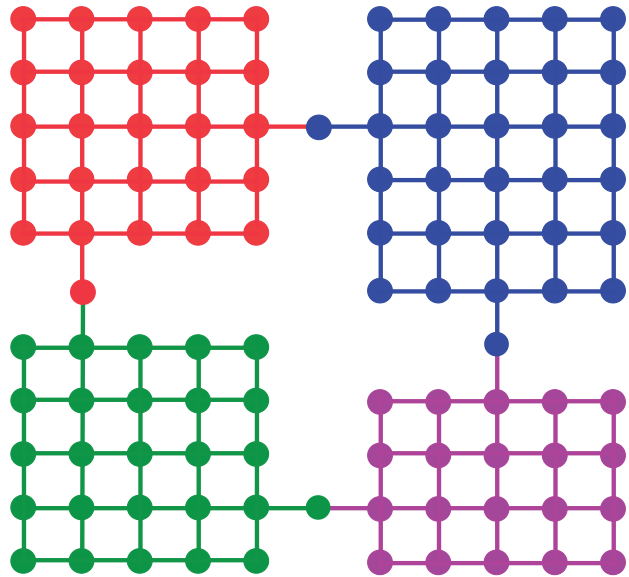
Carlos Diuk



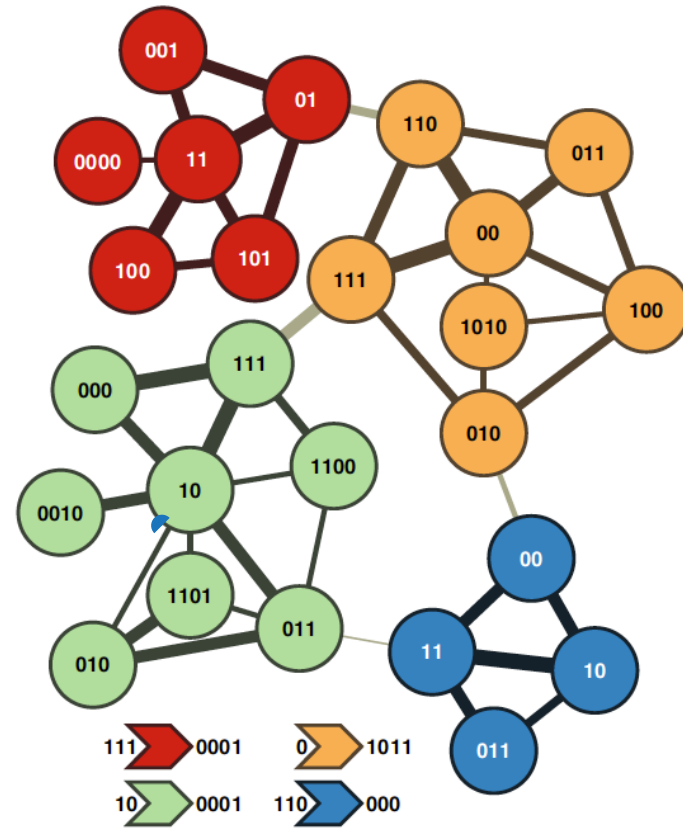
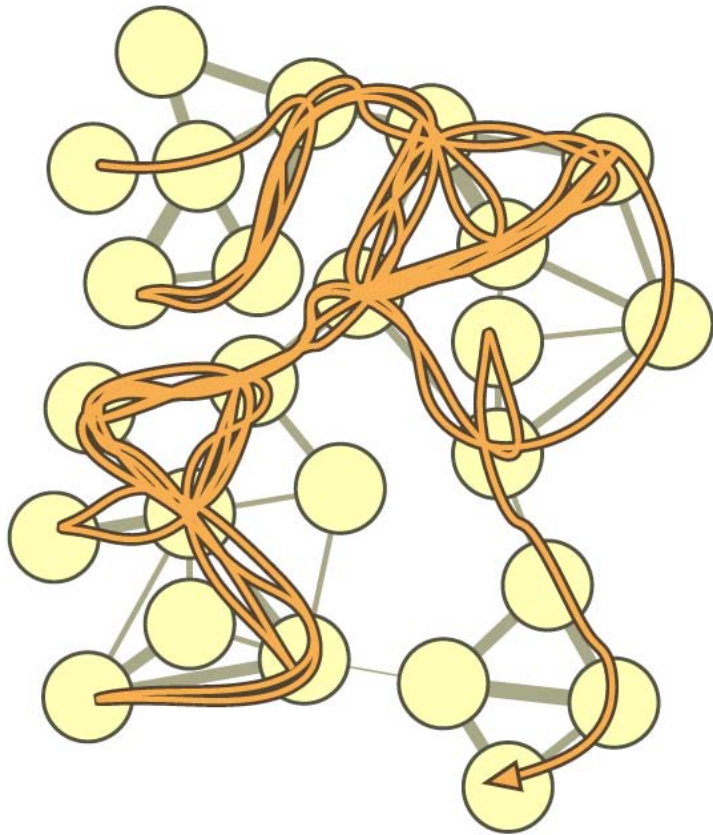
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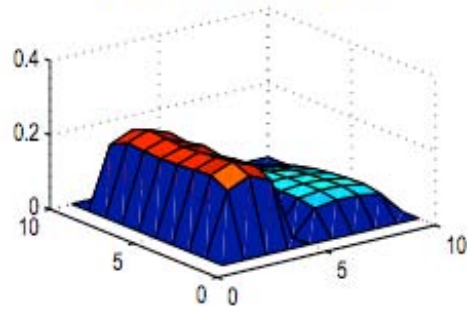
cf. Dayan, 1993



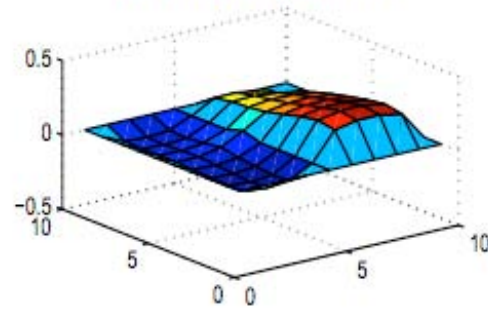
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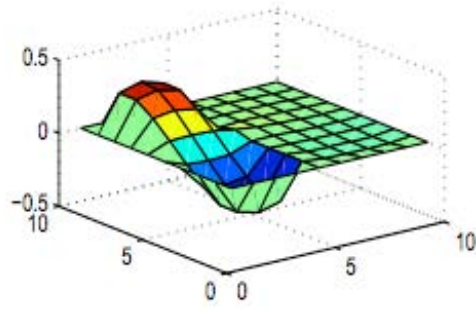
LAPLACIAN BASIS FUNCTION 1



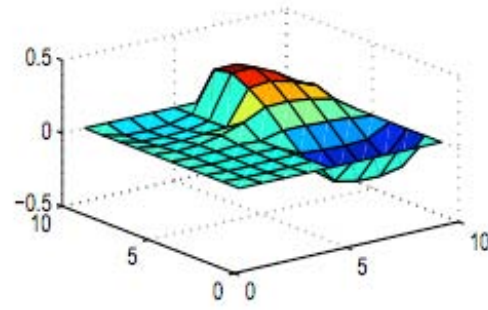
LAPLACIAN BASIS FUNCTION 2

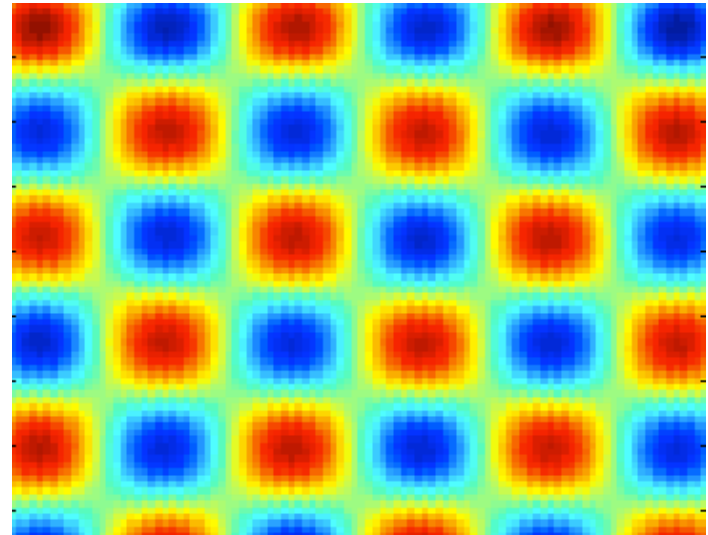
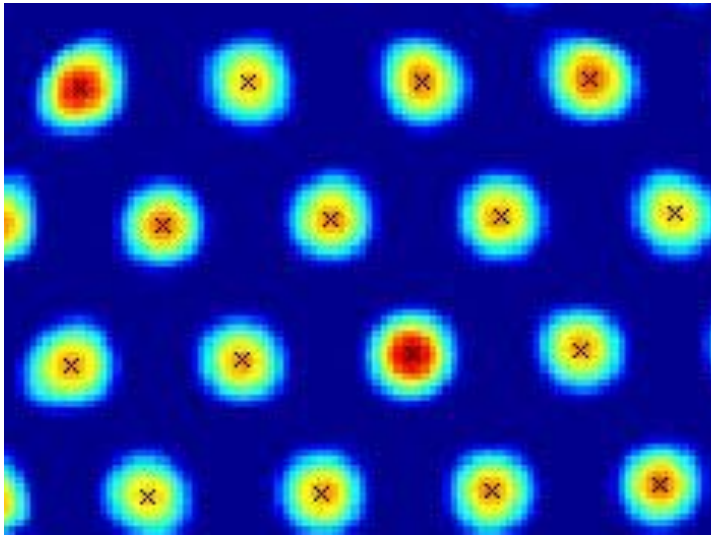


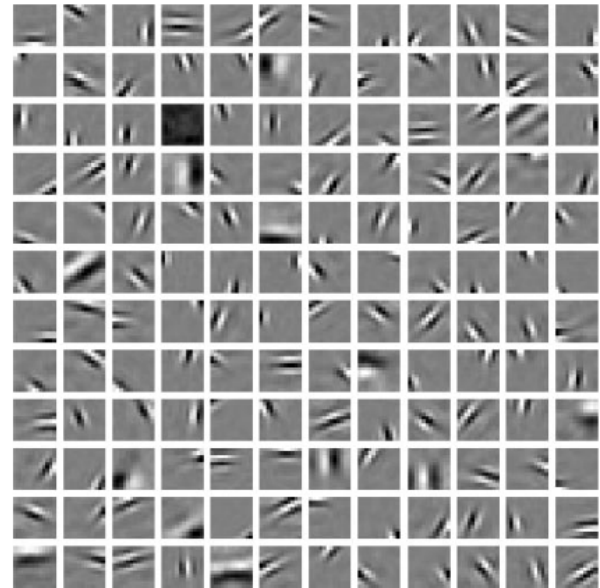
LAPLACIAN BASIS FUNCTION 3



LAPLACIAN BASIS FUNCTION 4



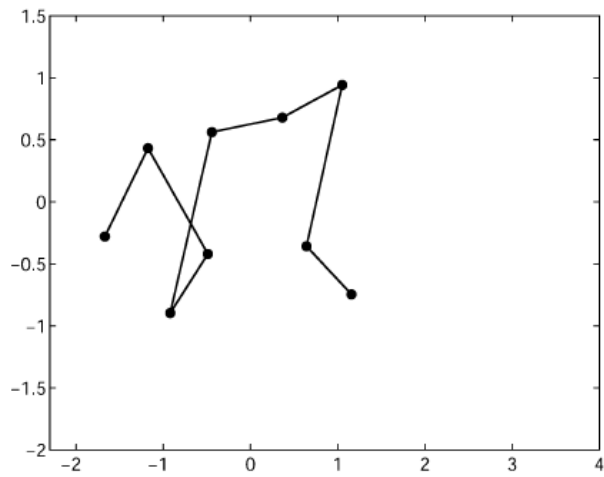




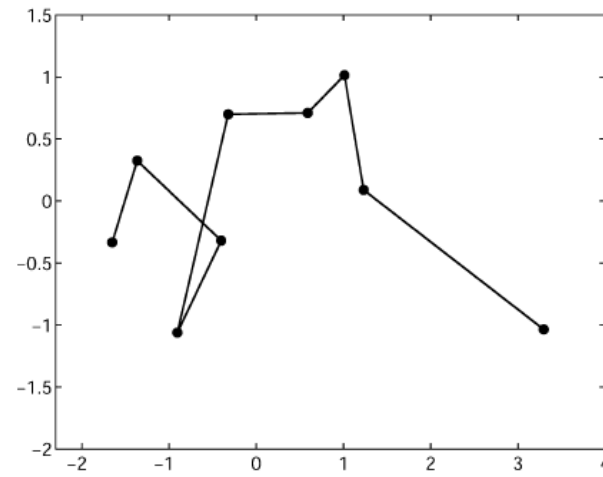
Olshausen & Field, *Nature*, 1996



Add sugar



Add cocoa



Conclusions



The scaling problem in RL



Hierarchy can help



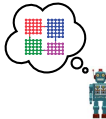
Model-free versus model-based HRL



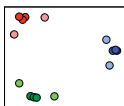
HRL in the brain



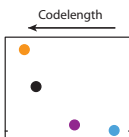
The need for good representations



Task decomposition, bottlenecks, community detection



Prospective coding and structure discovery



Hierarchy as compression



Lab Contributors

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 Alec Solway (V. Tech / UCL)
 Kim Stachenfeld
 Ari Weinstein
 Debbie Yee (Wash. U.)

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 Tim Rogers (Wisconsin)
 Nick Turk-Browne (Princeton)

